

Advancements in Dry Electrode Technology for Medical Devices

Yu M. Chi -- Cognionics, Inc.

About Cognionics

UCSD spin-off from Prof. Gert Cauwenberghs' research

Founded in 2010

Started operations in summer 2011

Funded by NASA, Navy, NIH, IEM, TATRC and DARPA grants, early prototype sales and consulting services

Currently 15 employees on payroll

3000 sq. ft. R&D office in San Diego

First commercial licensing deal signed in 2012

First commercial products on the market in 2013

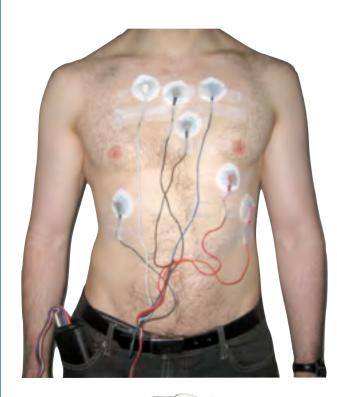








Motivation



ECG/EEG:

- Simple to build
- Inexpensive to use
- Non-invasive for the subject
- Widely used in clinical and research settings
- Diagnostically useful information

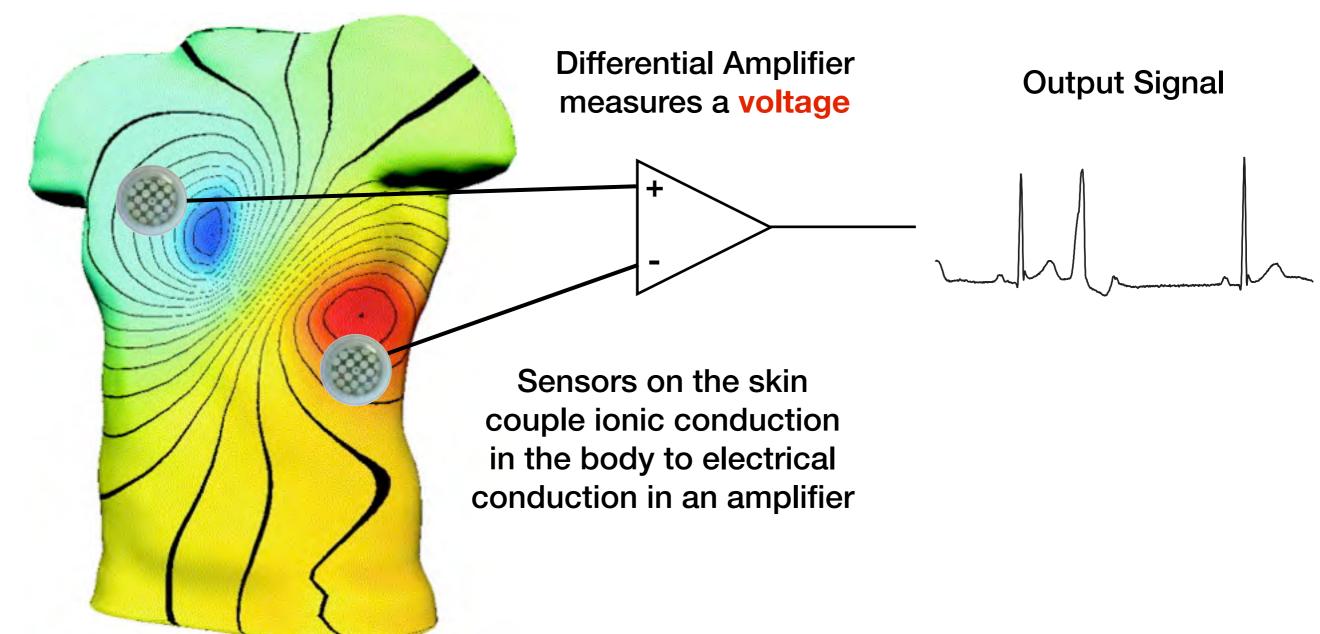


Today's ECG/EEG sensors, however:

- Require adhesives and skin-irritating gels
- Number one patient complaint against mobile ECG/EEG devices
- Need for new, patient-friendly, sensor technologies
- Large usability barrier outside of laboratory environments



Origin of Biopotential Signals

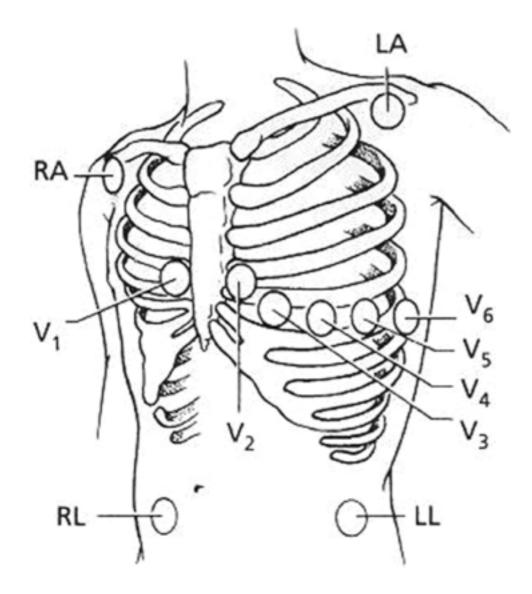


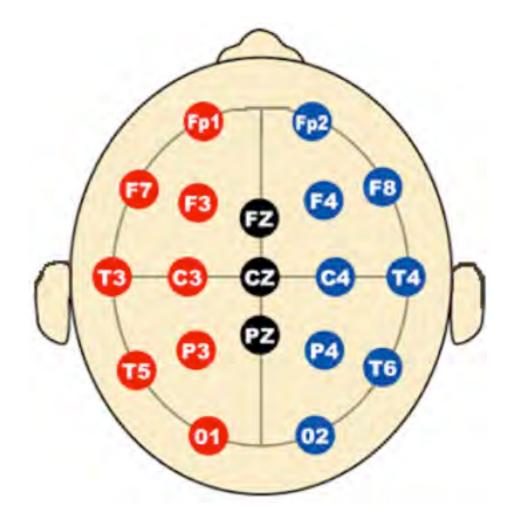
Physiological activity generates electrical fields inside the body which are propagated via ionic currents All biopotential signals require at least 2 points of contact and location of sensors is important



Placement of Sensors

Placement of sensors is critical to obtaining desired signal and rejecting noise







Challenges in Building a Low Noise System

Small signal with many potential sources of noise

Electronic Noise

- Amplifier thermal noise
- Common-mode noise
- Quantization noise

Requires more advanced circuit design including high resolution ADCs and driven grounds

Environmental Noise

- Mains pickup (60 Hz)
- Electrostatic charging
- Cable movement noise

Can be reduced by improved shielding and/or active electrodes

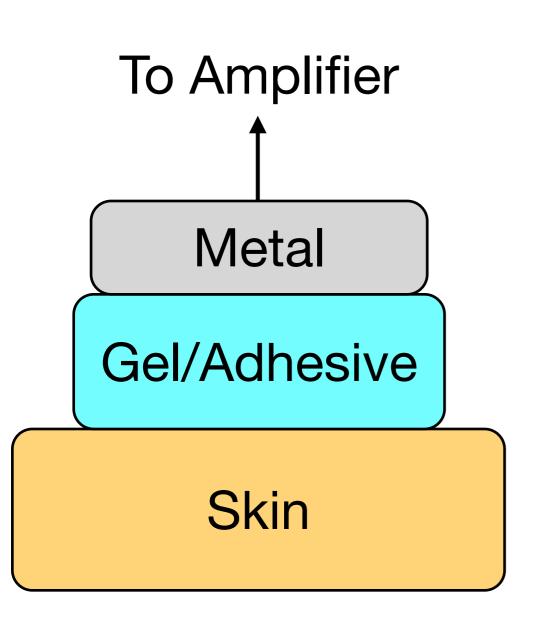
Sensor Noise

- Vibrations
- Skin potentials
- Electrochemical artifacts (improper metals)
- Poor contact
- Triboelectric charging

Solved with better sensor materials and harnesses



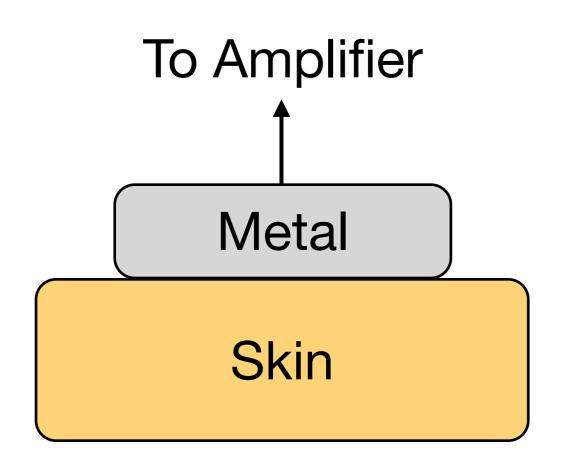
Wet Electrodes



- Gel lowers contact impedance, buffers against movement
- Low impedance contacts makes electronics design straightforward
- Wet sensors are self contained and adhere to the skin by themselves
- No need for harnessing, just wires to an electronics box is OK



Dry Electrodes



- No adhesive!

- More comfortable, potentially long-lasting
- Loss of contact leads to unacceptable artifacts in signal
- Higher impedance contacts are prone to noise pick up
- Depends on harness/system to make contact to the body

Design Challenges:

- Building a comfortable and secure harnessing system
- Contacting through hair (esp. EEG)
- Implementing low-noise acquisition electronics
- Optimizing the interface between skin and metal without conductive media



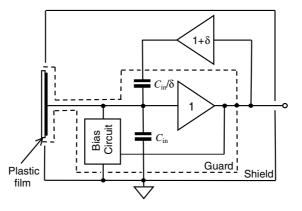
Types of Dry Electrodes

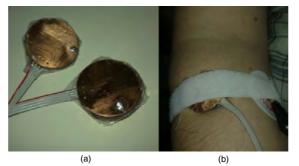
Dry Metal Contact



- Lots of examples in the market and research literature
- Can be very simple, bare metal works
- Gel-less contact with skin
- Performance also depends on quality of harnessing system

Capacitive





Spinelli et al. 2010

- Active buffering for impedance transformation at electrode source
- Can work OK through high resistivity materials (e.g., cotton) but not true insulators (e.g., synthetics)
- Movement artifacts are a huge issue in practice

Wet-Dry Hybrid



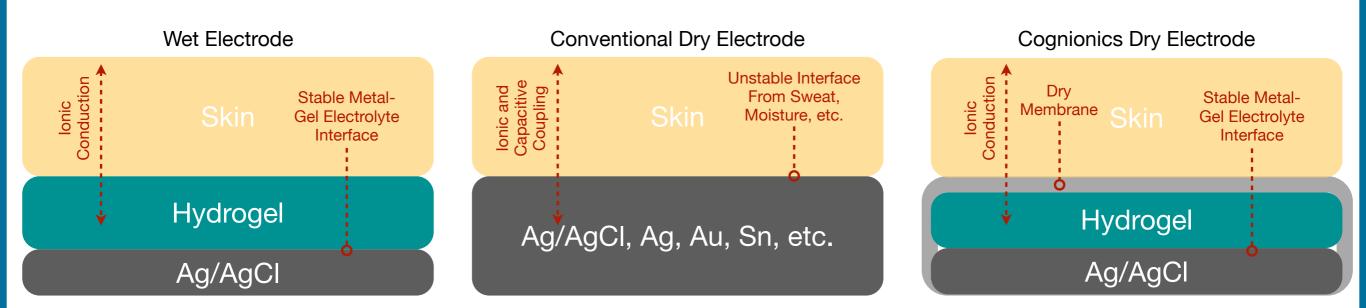


Cognionics

- Novel design that combines the best properties of wet and dry electrodes
- Dry contact surface with the skin
- Inner gel layer provides ionic conduction
- Stable gel to Ag/AgCl interface



Drypad Electrode Overview



Wet electrodes work well due to stable electro-chemical interface provided by Ag/AgCl and conductive gel. Efficiently converts ionic conduction inside the body to electrical conduction.

Normal dry electrodes have an unstable electrochemical interface due to absence of gel and the use of non-ideal metals. Manifests as high contact impedances, drift and noise.

Cognionics electrode provides a dry surface via a membrane. Ionic conduction still occurs across membrane into inner gel layer. The electrical characteristics are similar to standard wet electrodes including low impedances and noise.



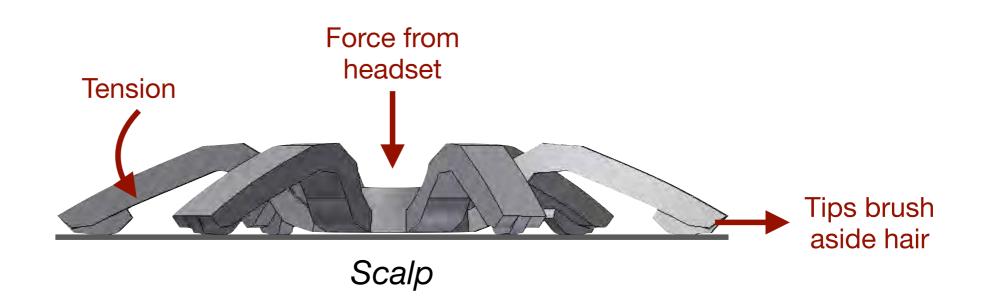
Flexible Electrode - Through Hair

Elastomeric Base





Increasing Pressure



High Density Headset Design

Precision Tension Adjustment



Wireless DAQ Electronics





Flexible Dry Sensor



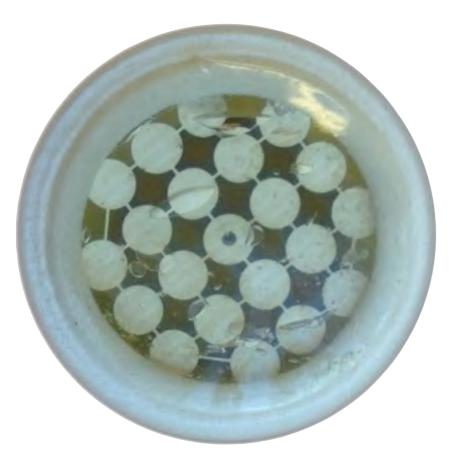
Pad Dry Sensor





But what is a <u>Complete</u> Dry Sensor System?

Harness/ Mechanics



The 'Sensor'



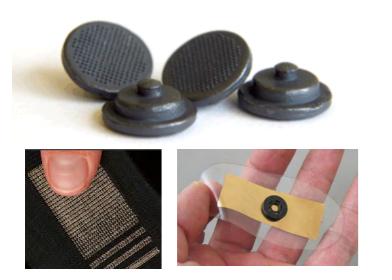


Electronics



Current Dry ECG Options

Standalone Sensors



- Many designs out there ranging from metal plates to textiles and polymers
- Minimal real benefit compared to inexpensive hydrogel electrodes, still requires tape and adhesives

More advanced versions include built-in amplifiers which can reduce some but not all types of noise

Event Monitors







-hulududu -

One lead event monitors well known, some are adding mobile capabilities (e.g., phone integrated)

More advanced systems can emulate 12-lead recordings

Lack of continuous recording limits utility but may be useful as a replacement for wet electrodes in short in-clinic readings

Complete Systems



Dry electrodes are well suited, in theory, for long-term ambulatory monitoring

Many different designs including belts, shirts, vests etc.

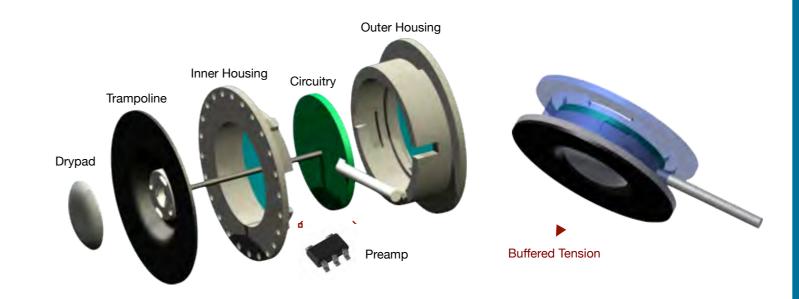
Artifacts are a huge issue: comfortable harness results in excessive movement and tight harnesses are uncomfortable

However, achieving low noise diagnostic recording is hard – especially for ambulatory use Need to correctly design a complete system, not just individual components



Cognionics Dry ECG System





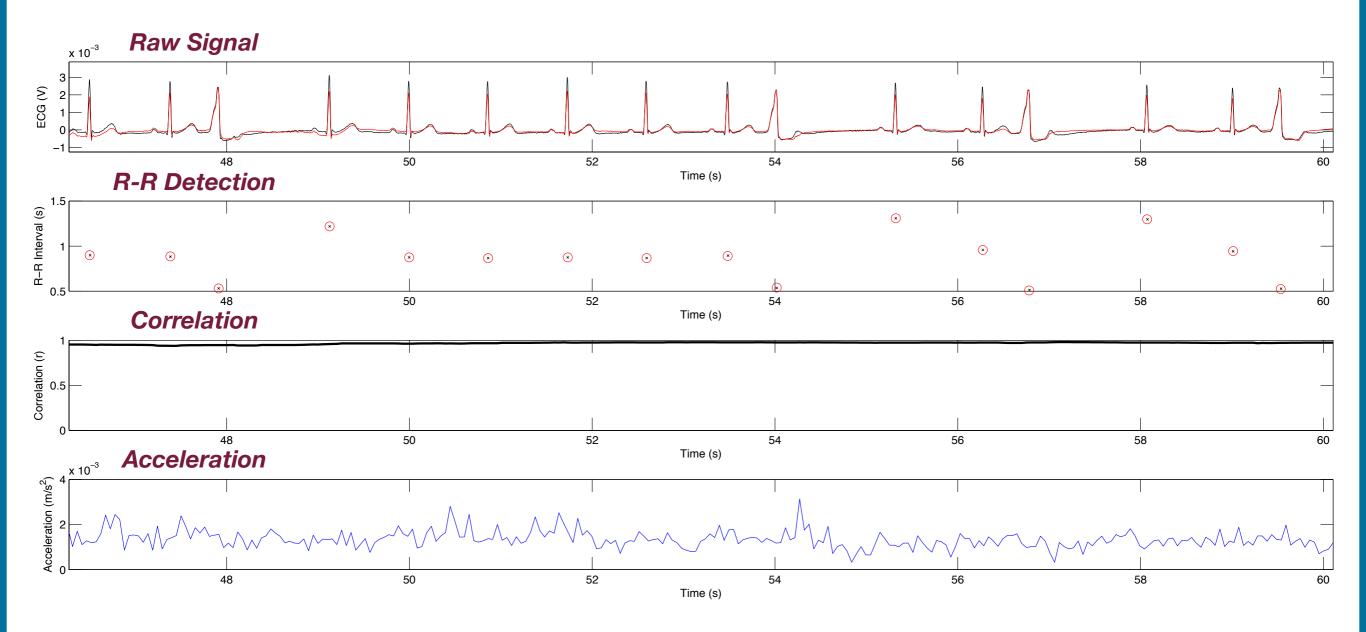
- -Evaluation 3-lead mobile ECG belt
- -Operates in both dry contact and non-contact mode difference in tightness
- -Onboard high-resolution data acquisition (24-bits, DC-100 Hz, 500 samples/sec)
- -Dry contact version can be worn over long periods without discomfort

- -Mechanical assembly for each Drypad sensor
- 'Trampoline' provides regulated tension holding sensor on body
- -Guards against movement artifacts and sensor contact loss



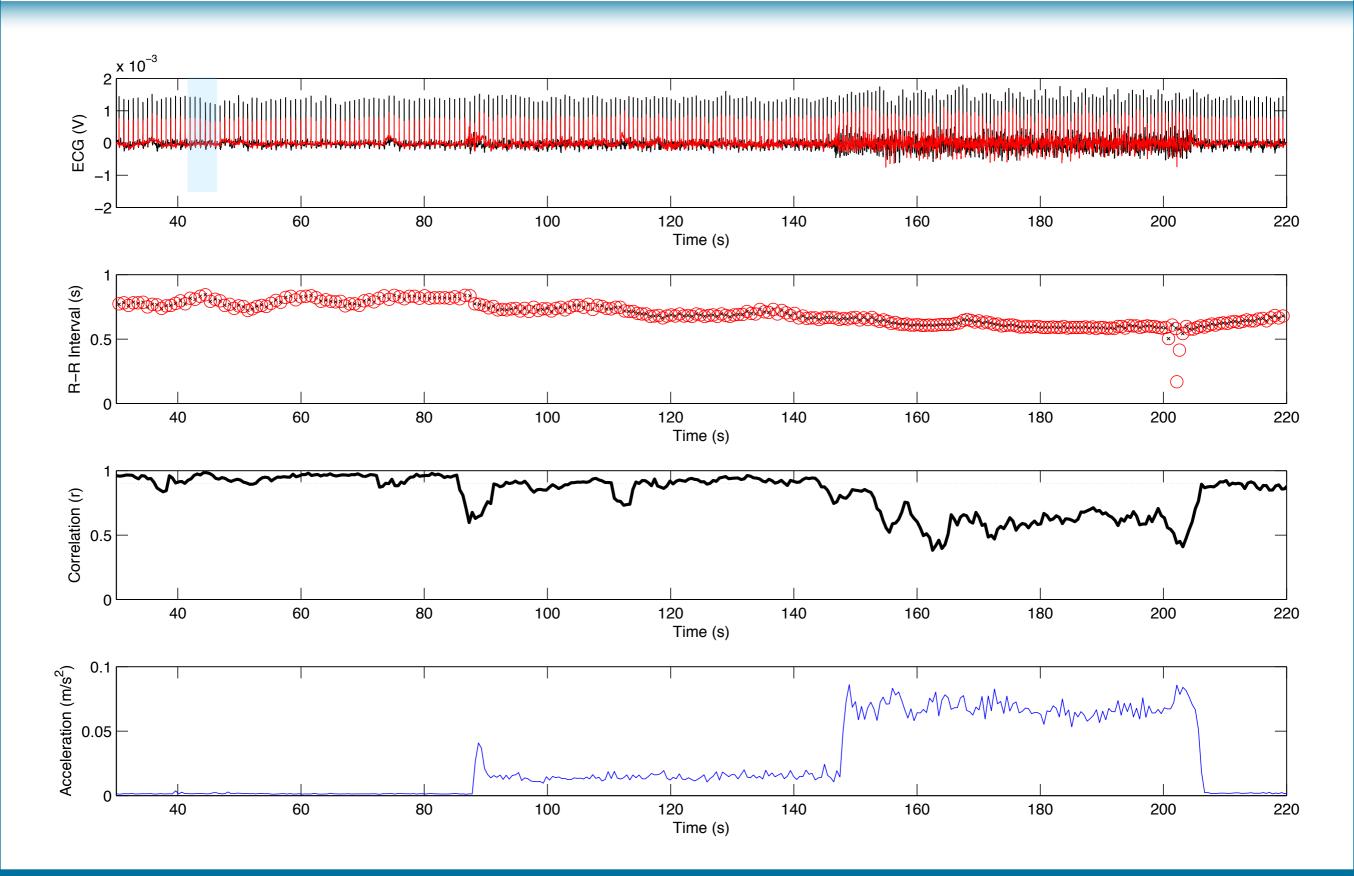
Dry ECG System Evaluation

Current 10 Subject Study: Two pairs of sensors - Wet/Dry Simultaneous signal acquisition with accelerometer data



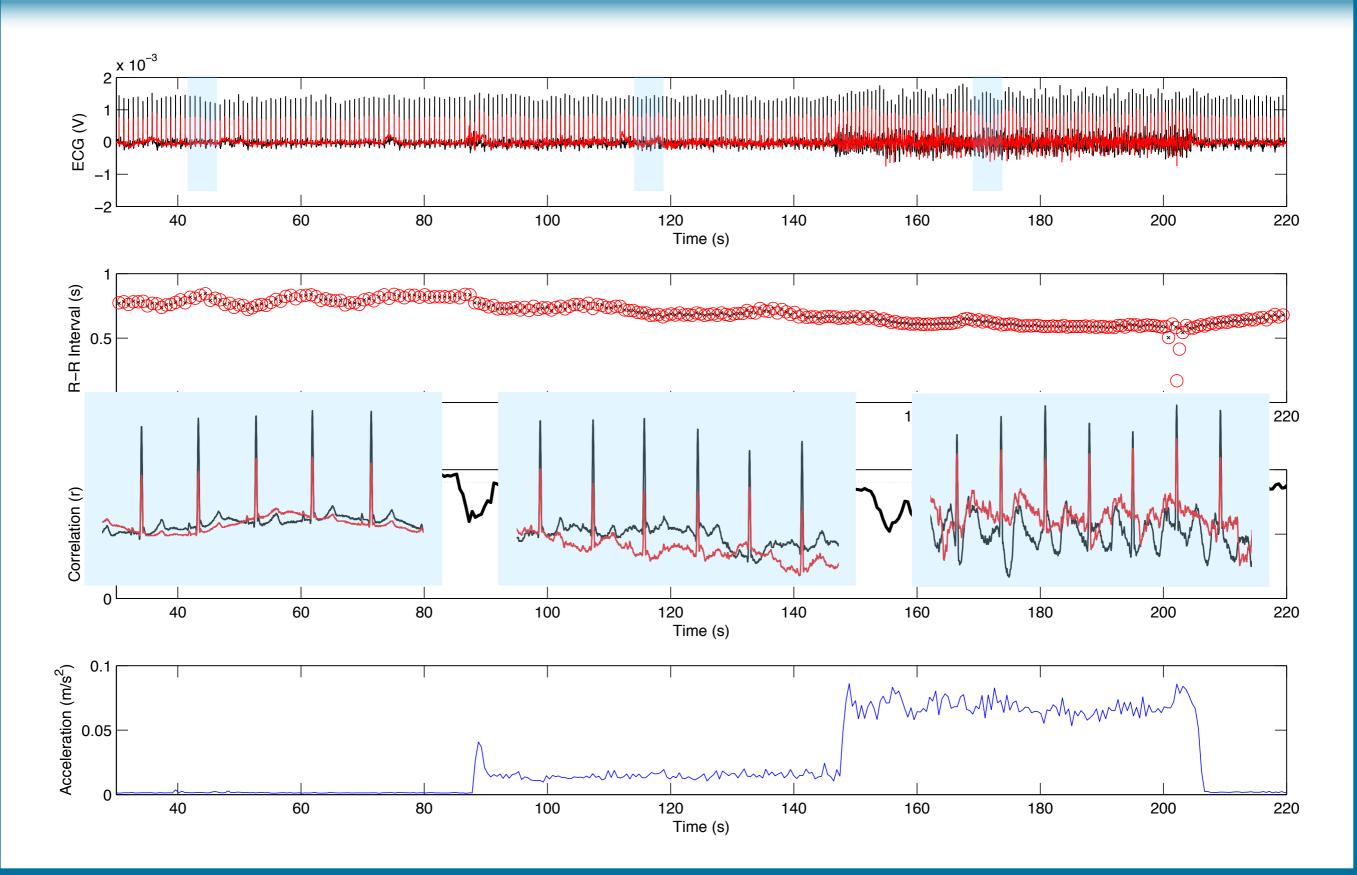


Sample Evaluation Data



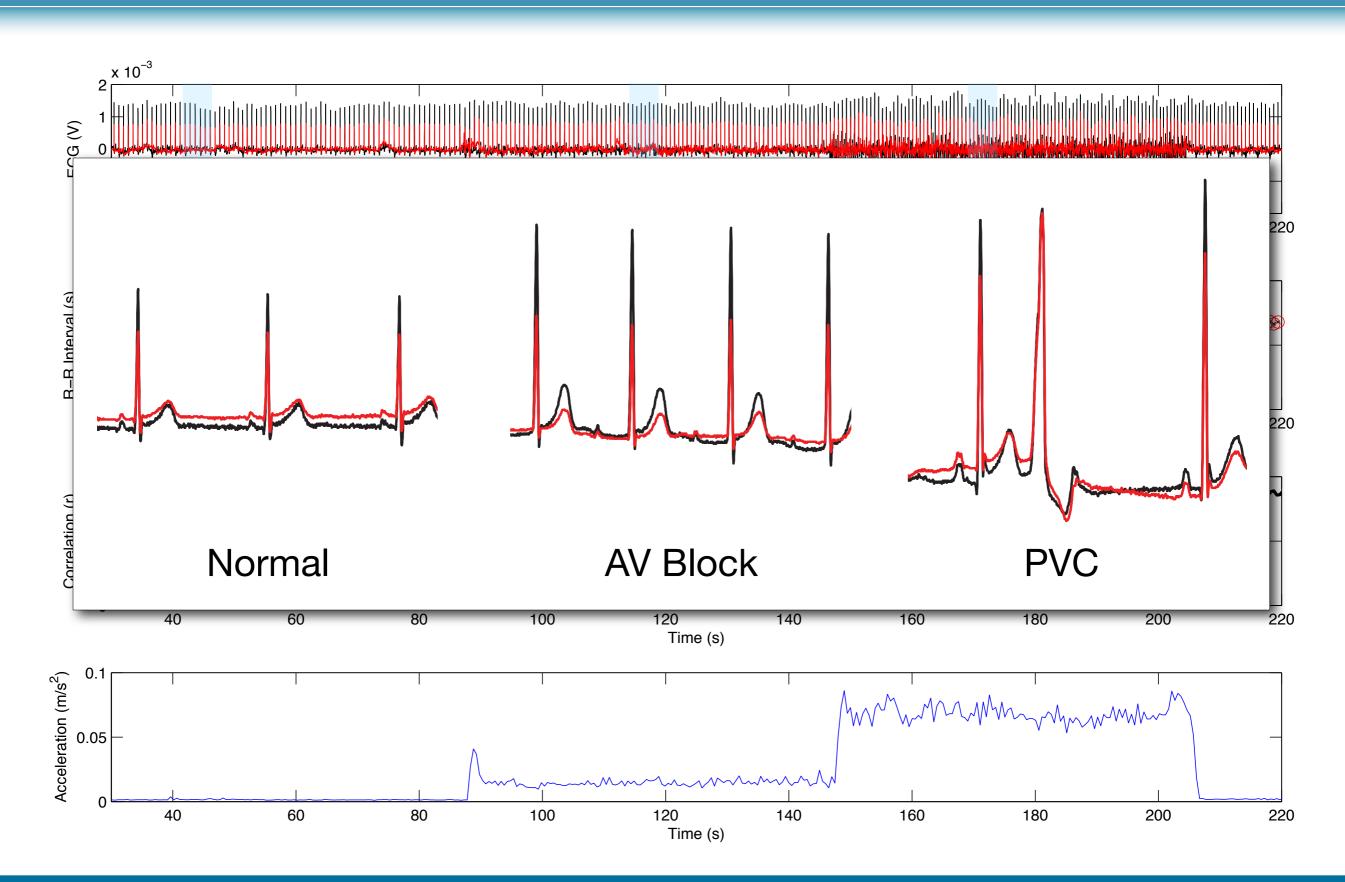


Sample Evaluation Data



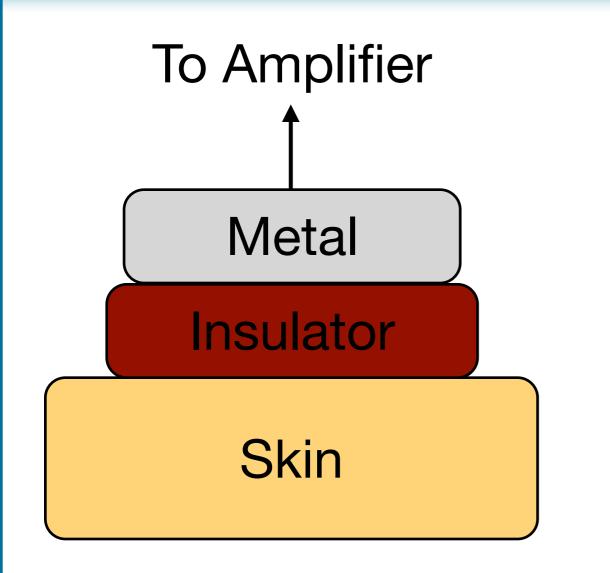


Sample Evaluation Data





Capacitive Electrodes



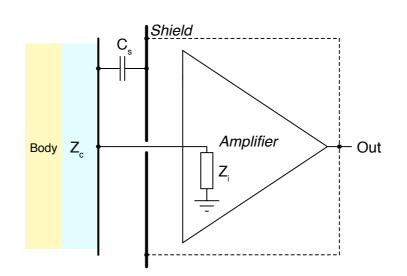
- No direct skin contact!
- Like dry electrode but even higher contact impedance
- Enables novel form-factors and use cases

Design Challenges:

- Optimizing input circuitry
- Controlling motion artifacts
- Minimizing noise pickup



Challenges in Non-contact Sensing



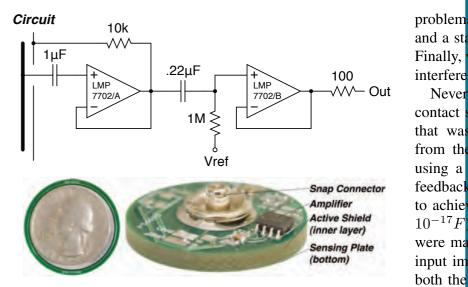


Fig. 3. A very simple dry active electrode made from a standard PCB [2]. on the The exposed metal on the bottom surface contacts the skin. The electrode can Burr-Br on. More complex

Biopotentials are at low frequencies: 0.05 - 100Hz (few kHz for EMG)

with physical skin contact means that the coupling capacitance for insulated electrodes is relatively large, from 300pF [17] to Standard wet adhesive electrodes offer a low impedance (5k tosigli00k) network with low noise and frequency 4 tesponse for clinical grade signals

v/√Hz

amphifier.

limited data exists that suggest capacitively coupled elec-Non-contact sensors couple via extremely high impedances: to 50pF same order of magnitude as an amplifier's input impedance the No when n de le ctrode. lable

Zc ~ Zi

Gain, CMRR, noise and interference rejection are all significantly V. NON-CONTACT, CAPACITIVE ELECTRODES compromised Wet and dry electrodes both require direct physical skin

V. (

From an electrical perspective, the high capacitance of the thin insulation layer is an effective short at signal frequencies and have no effect on the signal quality vis-a-vis dry electrodes. One obvious downside, however, is that the insulated nature of the electrode precludes a frequency response down to DC, which may be important for certain applications.

contact to operate. The final type of sensor, the non-contact

very feasible with a standard high impedance input FET

In most respects, the usage and performance of insulated

electrodes is quite similar to dry electrodes in practice. Some

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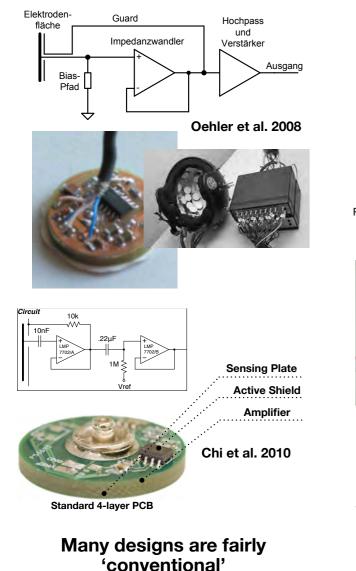
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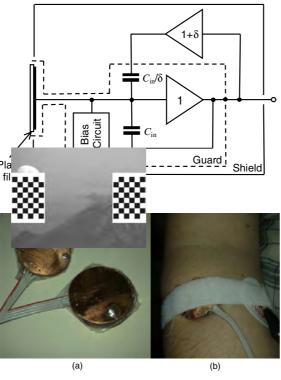
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Review of Sensor Implementations

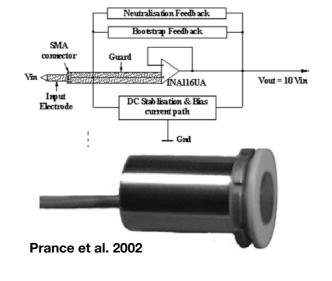
Active field with numerous papers and dissertations on the topic:





Spinelli et al. 2010

Some designs use clever tricks - here a insulated wire wrapped around the input pin of the opamp implements a >1T biasing resistor



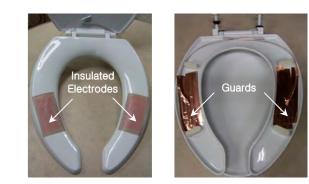


Quasar, Inc.

Other designs use

sophisticated circuit designs





Kim et al. 2004

A few imaginative applications can be found for example a toilet mounted ECG

Artifacts are a major issue in practice when sensors are deployed

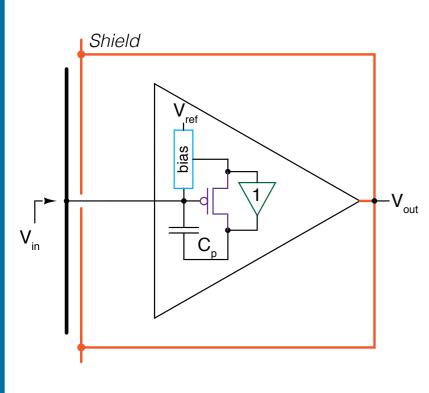


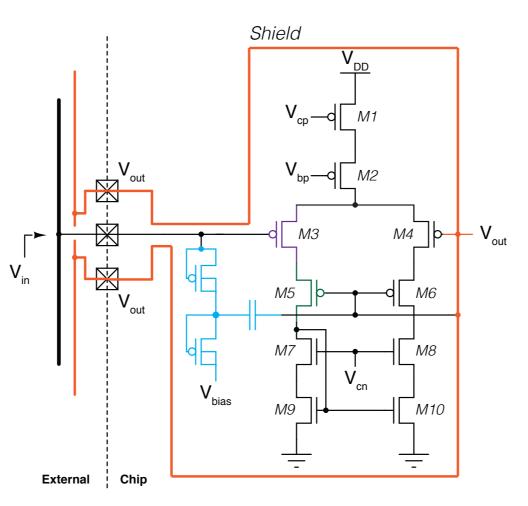
An Integrated Solution

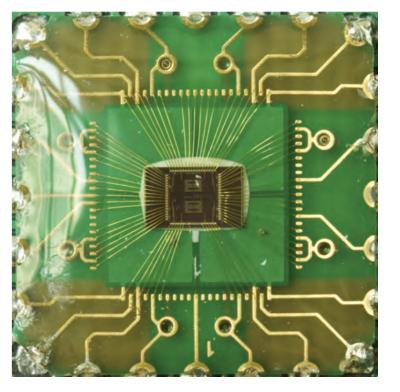
Sensor Concept

Circuit Implementation

Fabricated Chip







Extend active shielding structures and key bias structures to within the amplifier package itself Unity gain OTA (no component matching needed) with modifications to further reduce parasitic input capacitances

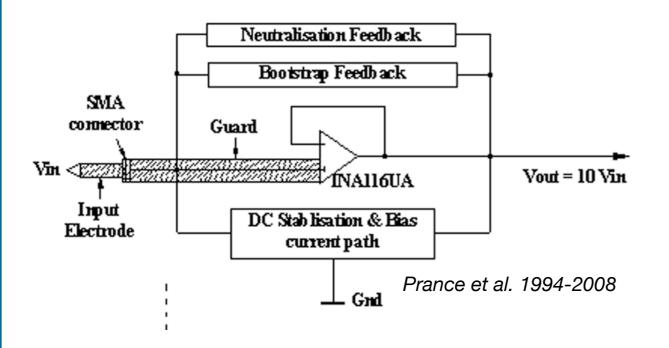
Chip mounted on special packaging to form complete active shield

Y. M. Chi, C. Maier, G. Cauwenberghs, IEEE JetCAS 2012



Complexity/Power/Cost Compared

Discrete Sensor Design

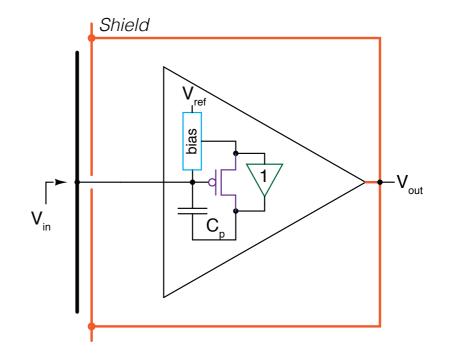


Previous designs have required **manually tuned** input neutralization and complex input biasing schemes

Neutralization requires multiple amplifiers per sensor and consume **too much power for mobile use (400µW-15mW)**

Expensive electrometer amplifiers (TI INA116) are \$7-10/unit

Integrated Sensor Design



Custom design allows for full bootstrapping on the input node and does **not need any adjustments**

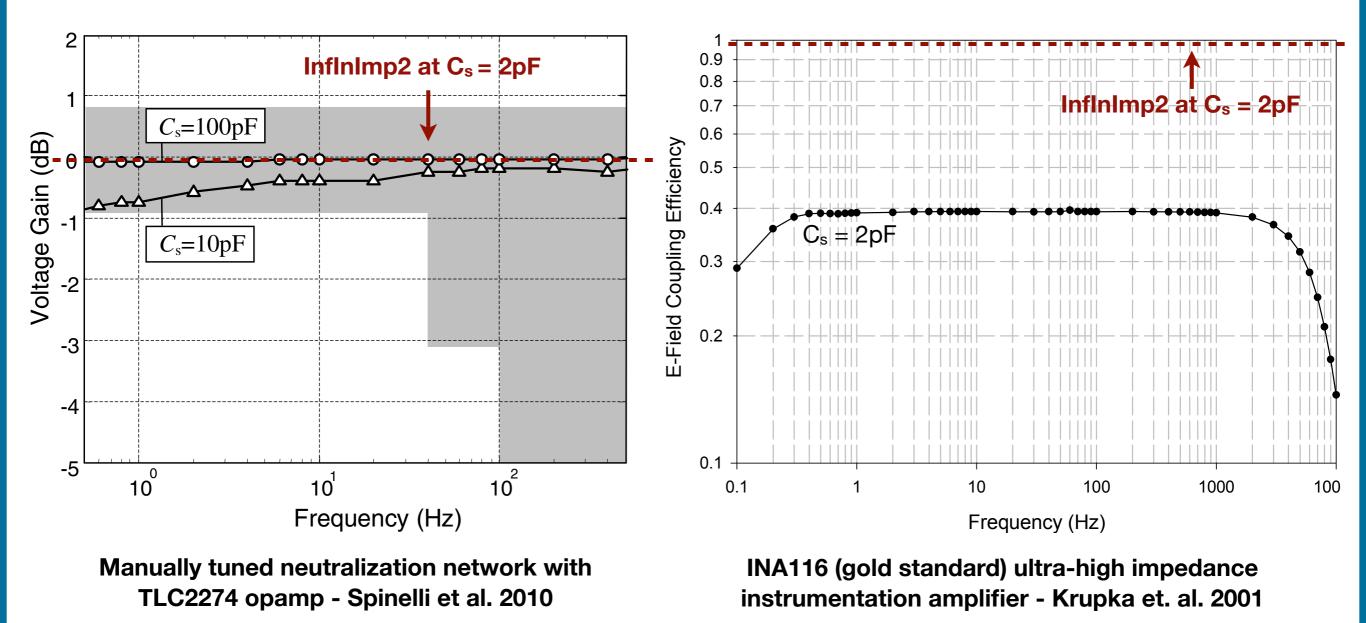
Micropower design only consumes enough power for ECG/EEG. Current prototype operates off a 3V supply at 1.5µA/sensor

Low cost 0.5µM CMOS process is used to fabricate the chip



Frequency Response Compared

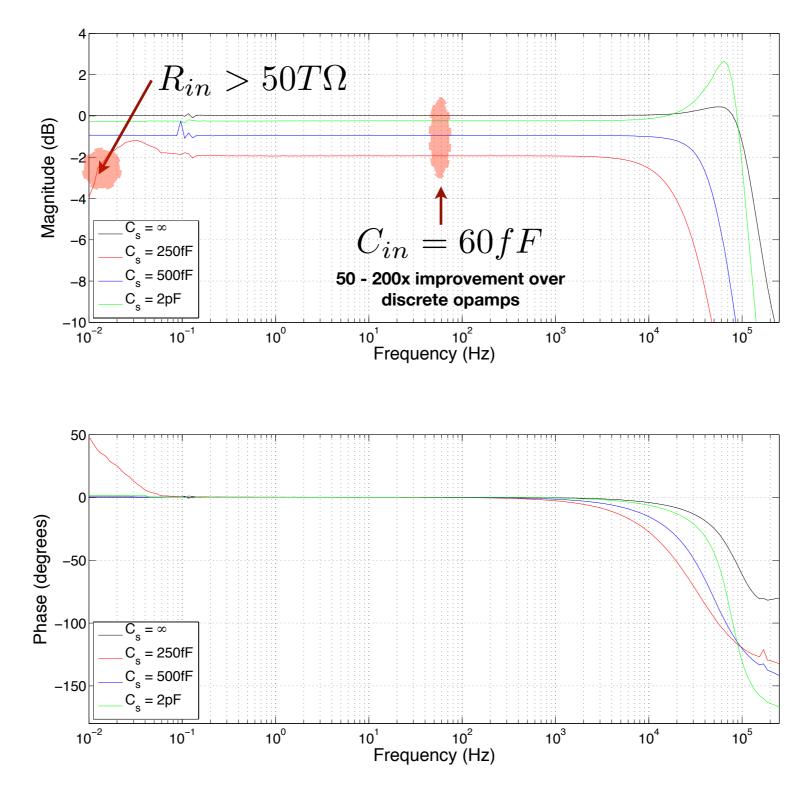
Typical results previously reported in the literature:



InfInImp2 - first integrated ultra-high input impedance that achieves femtofarad input capacitance without any manual calibration of adjustment



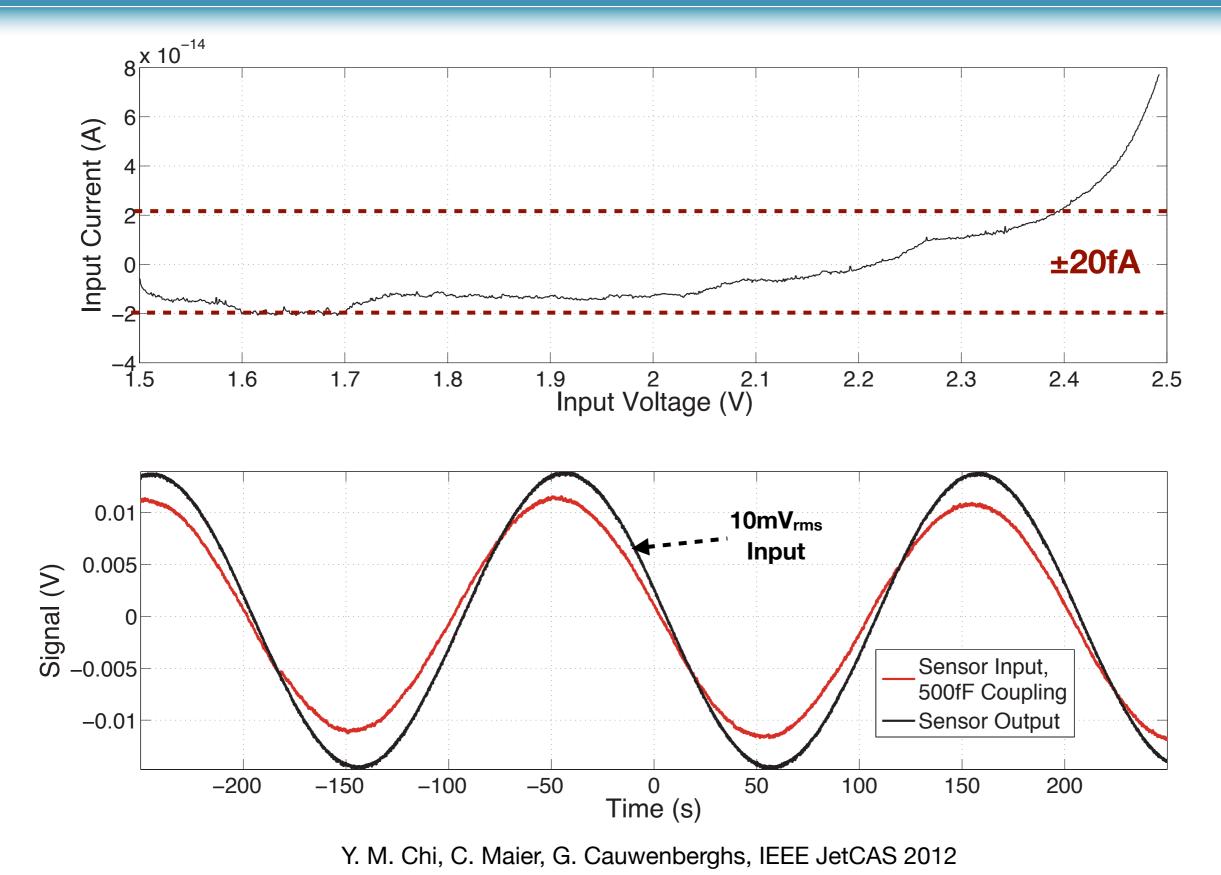
Frequency Response



Y. M. Chi, C. Maier, G. Cauwenberghs, IEEE JetCAS 2012



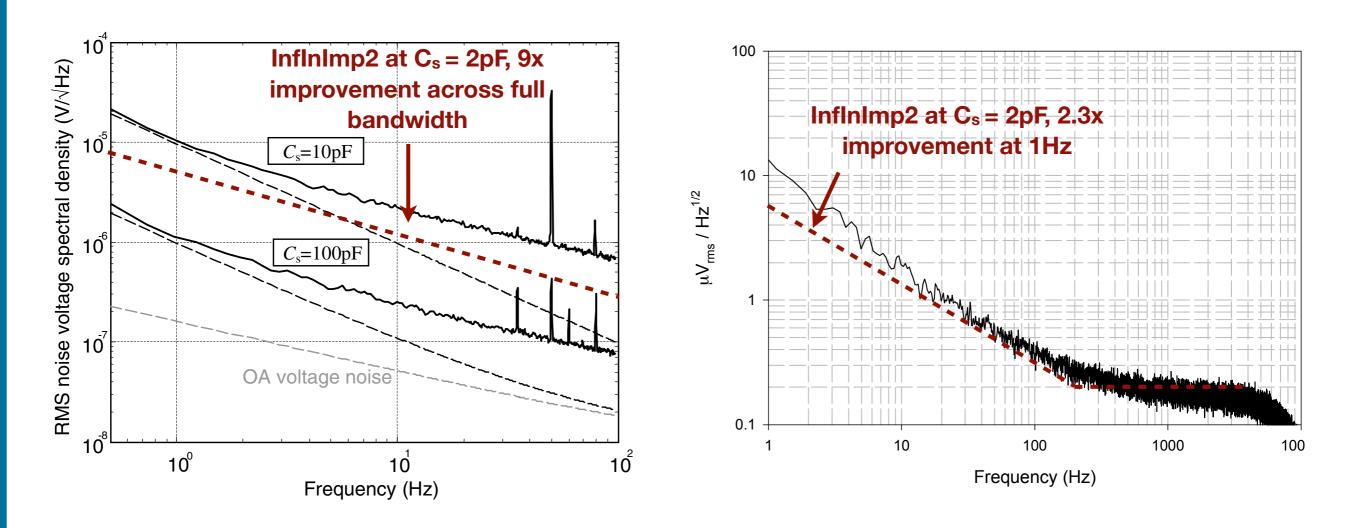
Input Bias Current





Compared

Typical results previously reported in the literature:

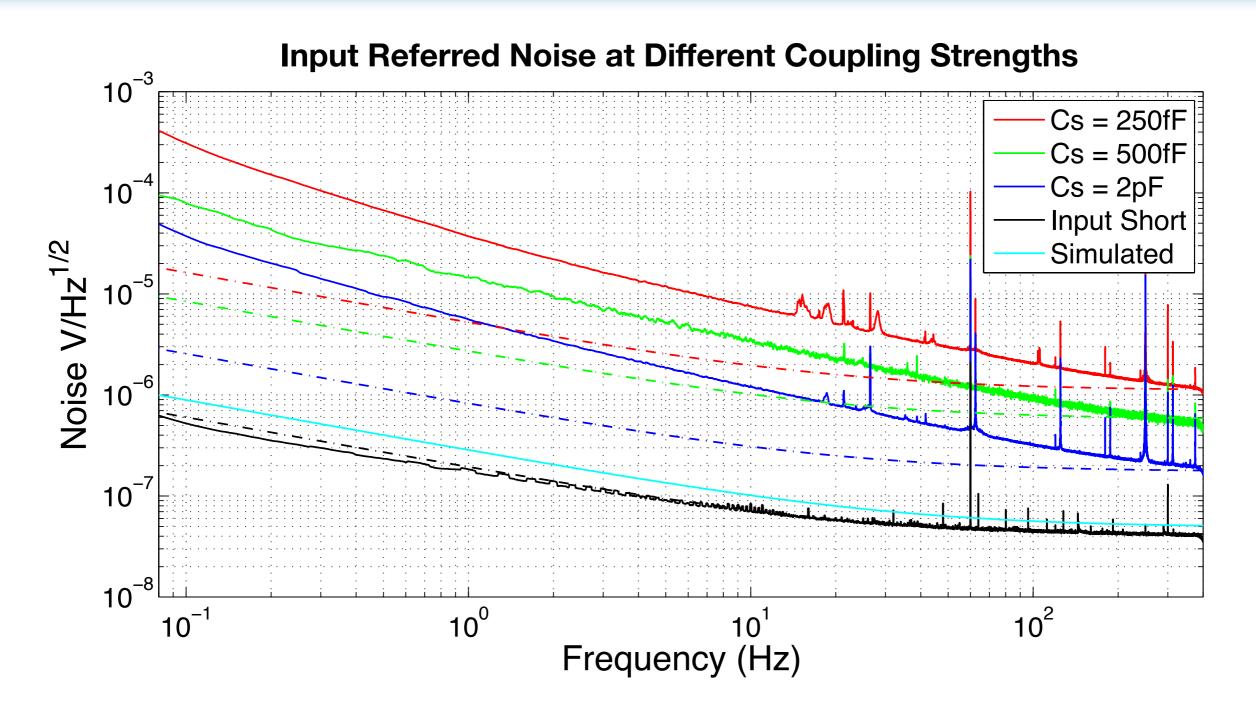


Manually tuned neutralization network with TLC2274 opamp - Spinelli et al. 2010

INA116 (gold standard) ultra-high impedance instrumentation amplifier - Krupka et. al. 2001



Measured Noise Spectra



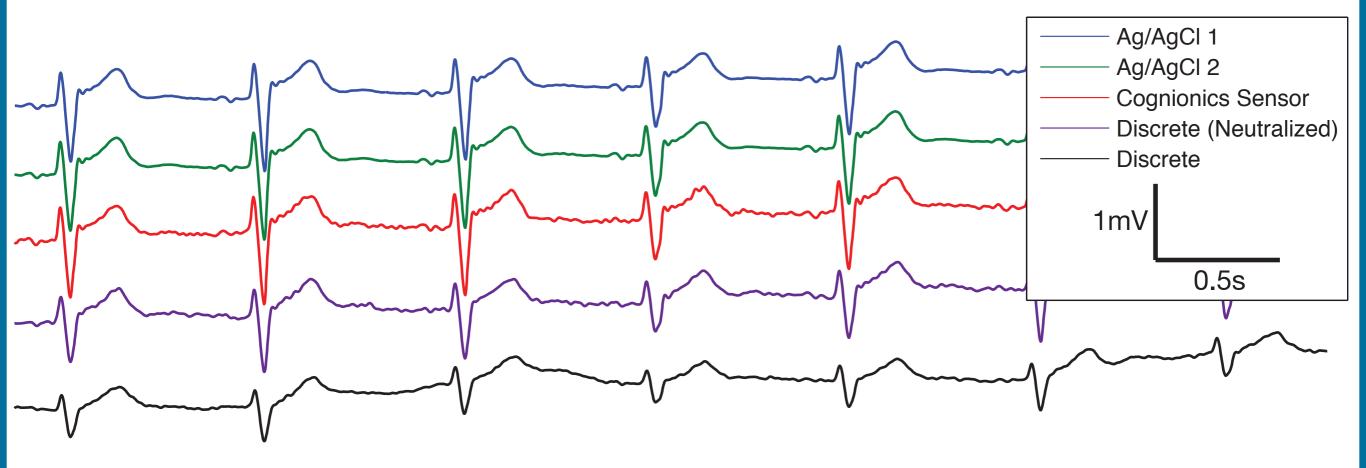
Intrinsic input capacitance is approximately 6pF based on the noise gain model Low frequency noise behavior still dominated by current noise effects (~50aA/Hz^{1/2})

Y. M. Chi, C. Maier, G. Cauwenberghs, IEEE JetCAS 2012



ECG Signal Validation on Actual Subject

Simultaneous ECG recording using different sensors (0.05Hz to 35Hz BW)



All 5 sensors were placed on the forearm referenced against a common chest electrode - should observe same signal since the arm is at an equipotential with respect to ECG

2 reference Ag/AgCl electrodes as control

Three capacitive sensors: discrete (neutralized), discrete and integrated all placed through a thick cotton sweater (Impedance ~ 1G || 30pF)



Measured Correlation

Table - Sensor Correlation Comparison

Electrode Pair	r	b
Ag/AgCI - Ag/AgCI	0.992	0.999
Ag/AgCI - Integrated	0.953	0.996
Ag/AgCI - Discrete (calibrated)	0.918	0.865
Ag/AgCI - Discrete	0.715	0.541

r - Pearson's correlation coefficient (insensitive to pure scaling errors), measures noise and distortion
b - linear regression coefficient, measures gain error due to electrode-input impedance division

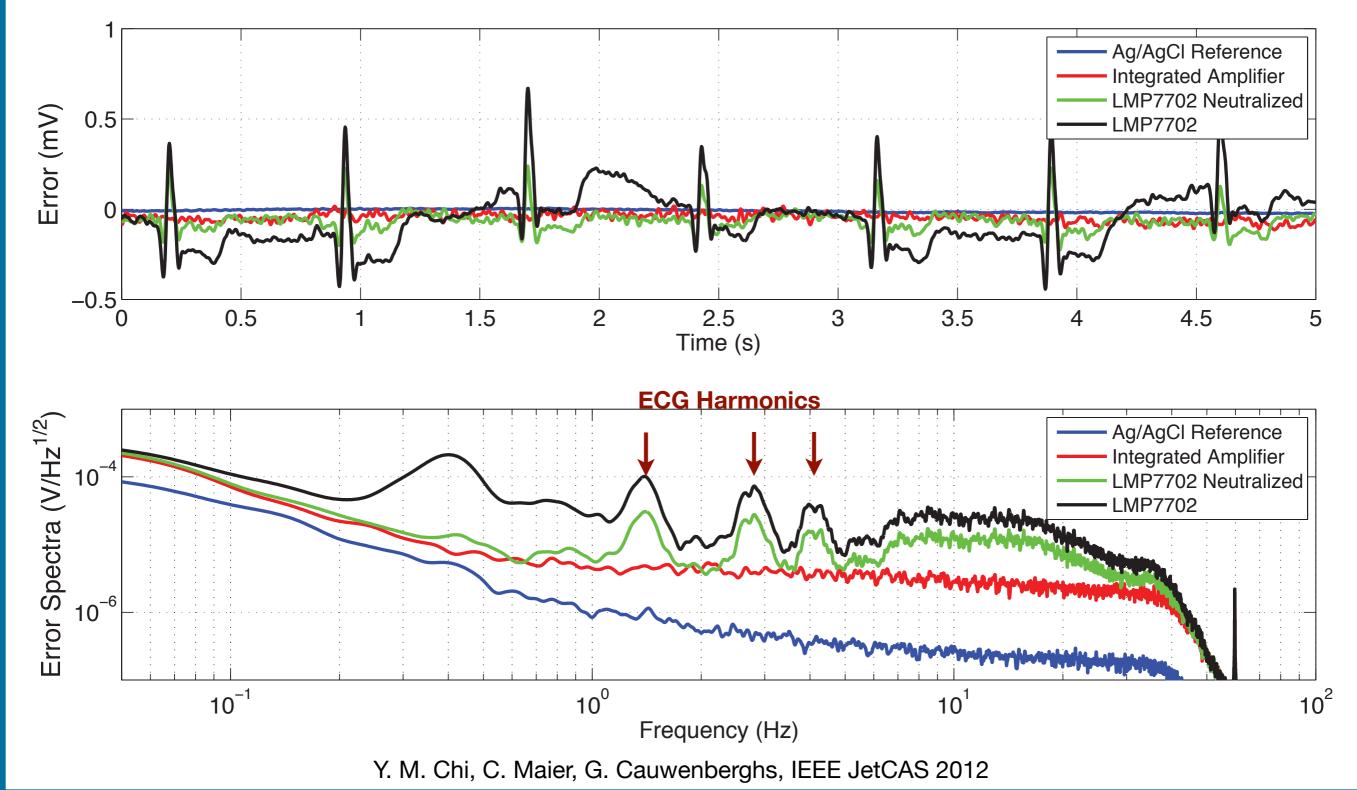
Low input capacitance integrated front-end significantly more accurate than previous discrete implementations

Y. M. Chi, C. Maier, G. Cauwenberghs, IEEE JetCAS 2012



Residual Sensor Error

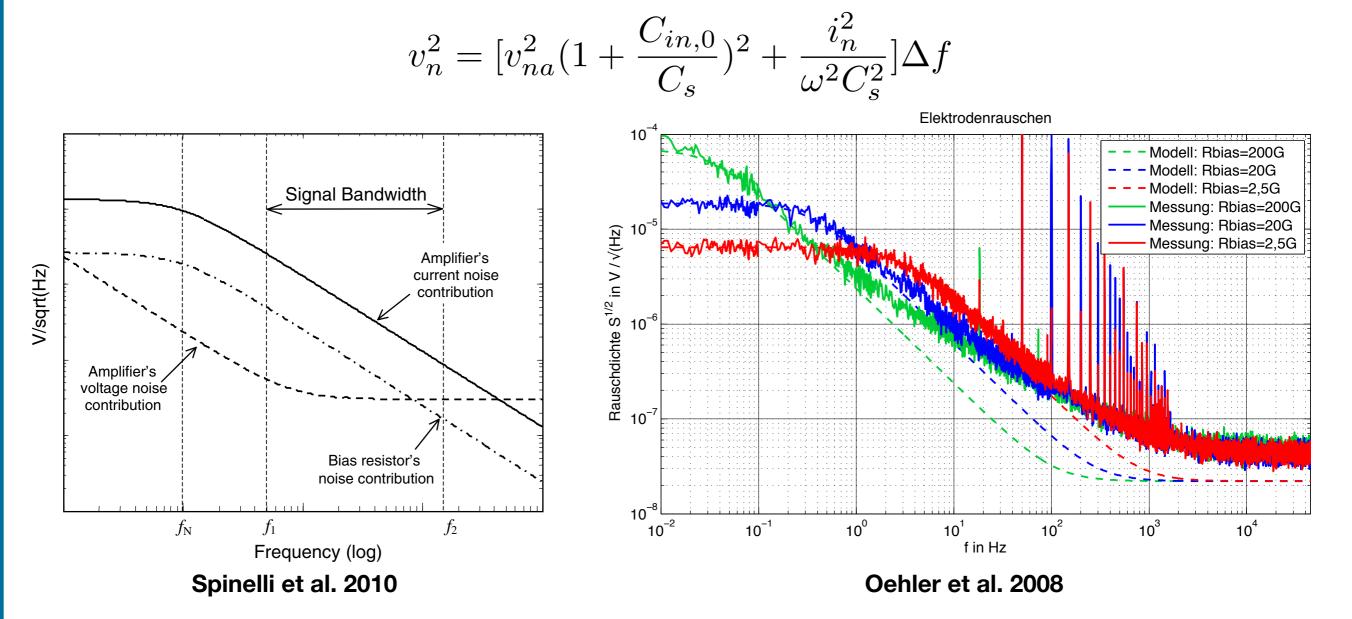
Difference Between Two Electrodes Should be Zero (CMRR = ∞)





Previous Attempts at Noise Modeling

Noise limits based on coupling to purely capacitive source:

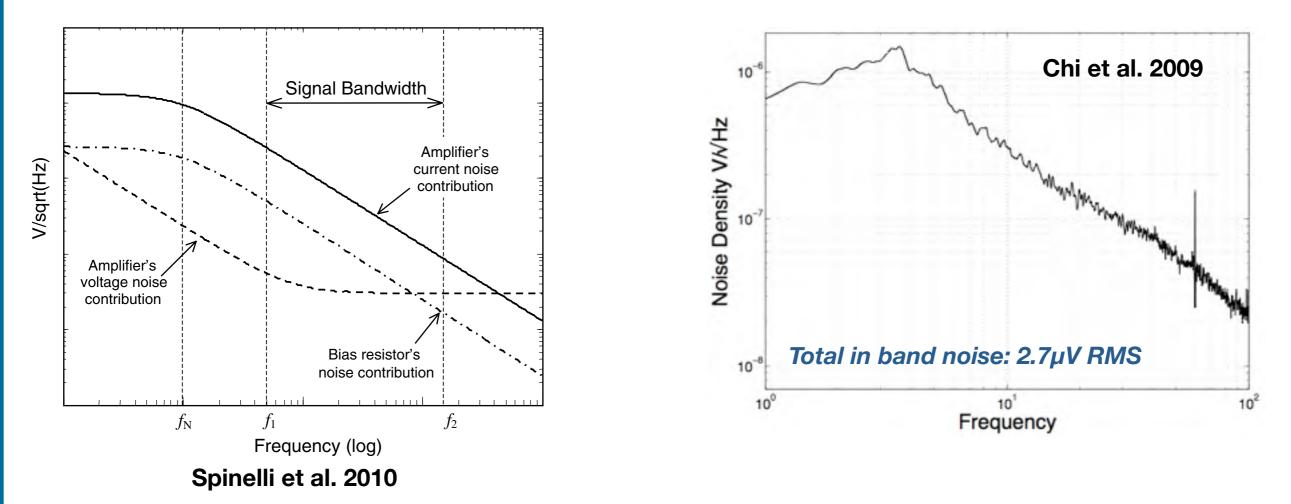




Previous Attempts at Noise Modeling

Noise limits based on coupling to purely capacitive source:

$$v_n^2 = \left[v_{na}^2 \left(1 + \frac{C_{in,0}}{C_s}\right)^2 + \frac{i_n^2}{\omega^2 C_s^2}\right] \Delta f$$



Previous understanding in literature has always used the model of an ideal capacitive source for noise modeling - assumption that noise can be reduced with improved circuit design and components (e.g., lower current noise).

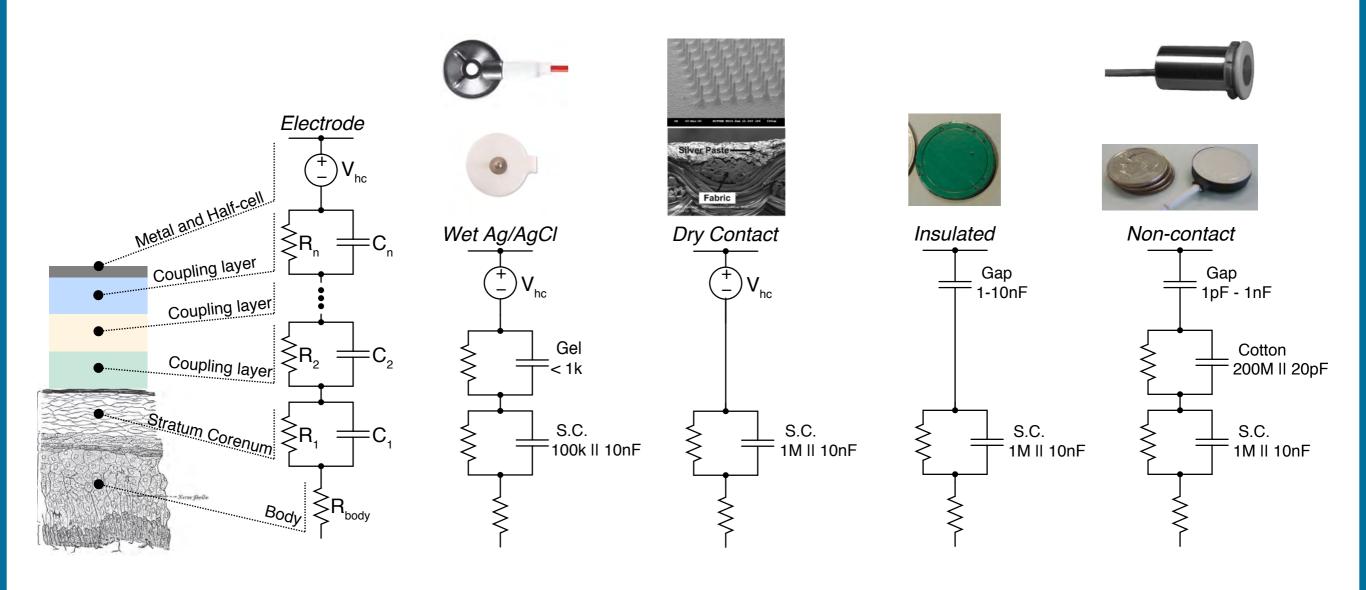
While benchtop measurements corroborate theory - actual noise for ECG/EEG on subjects is always much higher than that predicted by the noise equations.



Noise in 'Capacitive' Biopotential Electrodes

Noise equations work if the coupling is through a near ideal dielectric (e.g., air gap) - not practical for E*G applications

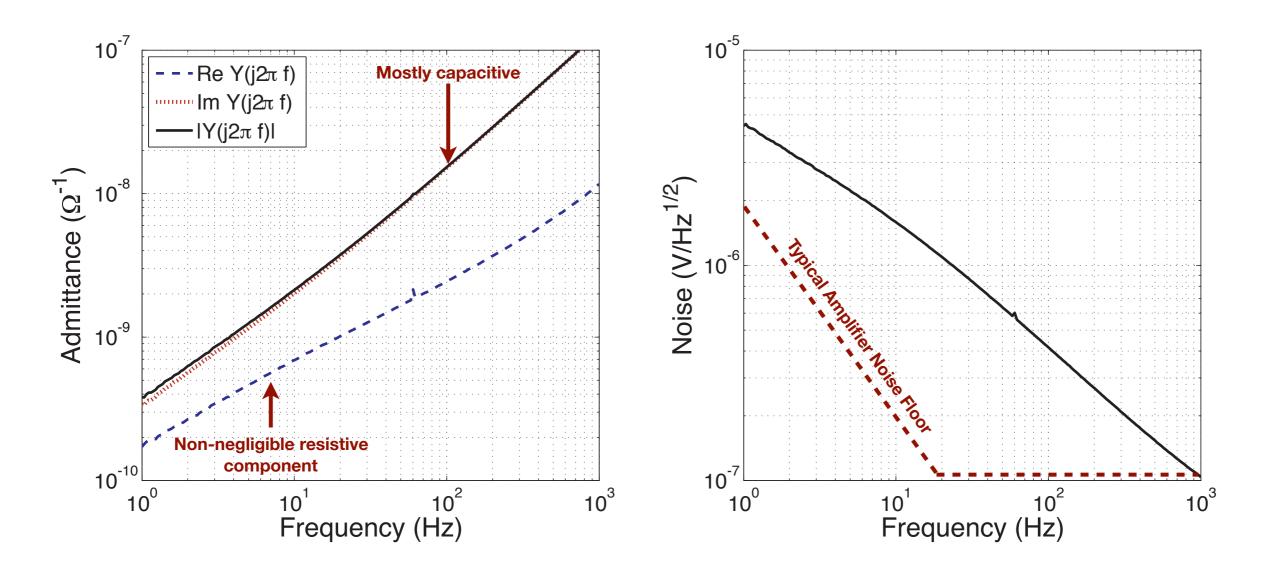
Must also consider the properties of the coupling medium between the sensor and body - cotton, hair, etc.





Electrical Properties of the Interface

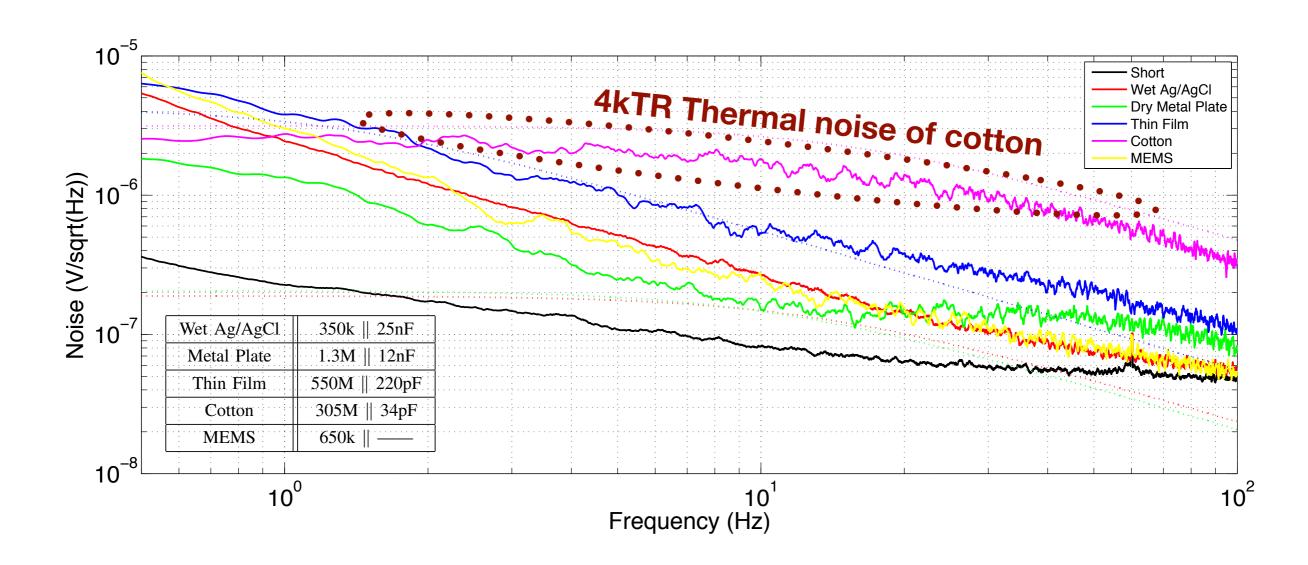
Measured impedance of cotton fabric using a lock-in amplifier:



Signal coupling is not through an ideal capacitor!



Measured Interface Noise Spectra



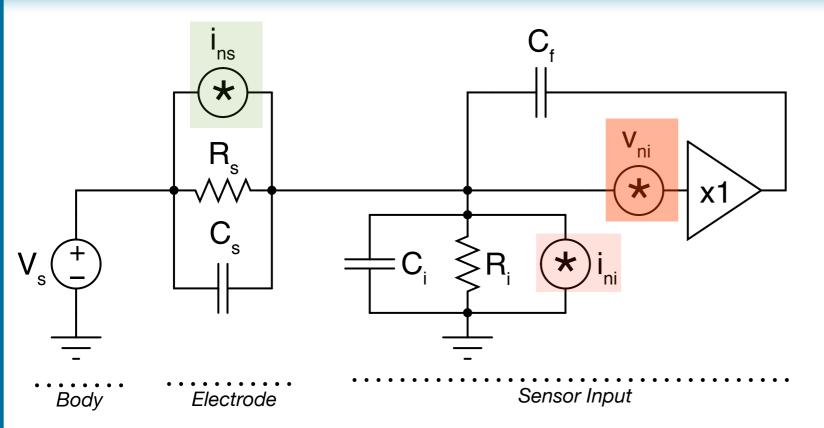
Coupling media may actually generate the largest amount of noise within the signal bandwidth:

Interface Noise - 3µV/Hz^{1/2}

Yu M. Chr, Tzyy Ping Jung, Gert Cauwenberghs, IEEE Reviews in Biomedical Engineering, 2010



Noise with Real Electrode Interfaces



i_{ns} = 4kT/R_s i_{ni} = 4kT/R_i (resistor) or 2kT/r_d (diode) v_{ni} = amplifier input thermal noise

Total Output Noise:

$$v_{out,n}^{2} = \left[\frac{4kT}{R_{s}}|Z_{s}||Z_{in}|^{2} + \frac{4kT}{R_{i}}|Z_{s}||Z_{i}|^{2} + \frac{v_{ni}^{2}|1 + sC_{f}(Z_{s}||Z_{i})|^{2}}{R_{i}}\right]\Delta f$$

Noise Figure:

$$F = 1 + \frac{R_s}{R_i} + \frac{v_{ni}^2 R_s}{4kT} \left(\frac{1}{|Z_s||Z_i|^2} + \omega^2 C_f^2\right)$$

 $Z_i \to \infty$

Infinite input impedance achieves optimal noise figure

 $F \to \infty, R_s \to \infty$

Amplifier noise dominates for purely capacitive sources

More Realistic Values:

 $Z_s = 1G||20pF, Z_i = 1T||5pF, C_f = 5pF, V_{ni} = 90nV/Hz^{1/2}, f = 5Hz$

F = 0.002dB !!

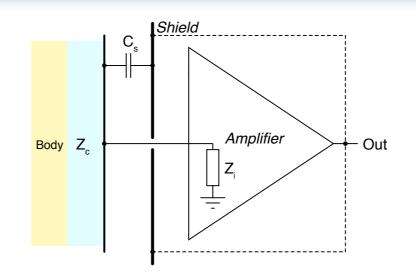
Key Difficulty:

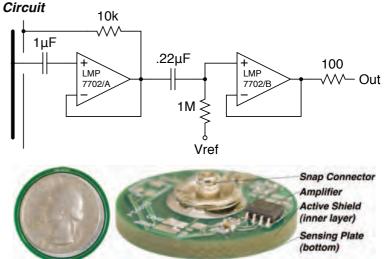
Some insulation (e.g., cotton) generate large amounts of thermal noise (1 TMΩ) yet do not have enough shunt capacitance (~20 pF) within ECG/ EEG frequency bands. *Noise is not circuit limited!*

Yu M. Chi, Tzyy-Ping Jung, Gert Cauwenberghs, IEEE Reviews in Biomedical Engineering, 2010



Input Impedance and CMRR





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Electrodes with input capacitance of 5pF, coupling with experimental of sufficient through motion such as extended in the sufficient through motion such as extended in [3] [4] [5].

 $CMRR \approx \frac{|Z_{in}|}{|Z_1 - Z_2|} \approx \frac{v/\sqrt{Hz_1C_2}}{C_{in}C_1 - C_2}$ with physical skin contact means that the coupling capacitance for insulated electrodes is relatively large, from 300pF [17] to sev2ral nanofarads. As a result, designing a bias network with low noise and frequency 4 tesponse for clinical grade signals sovery feasible with a standard high-impedance input FET CMRR ~ 26dB!, Can add DRL for additional 40dB of **MAR** 0 TOP In host respects, the usage and performance of insulated If input capacitance is 60fF, CMRR = 64dB quite similar to dry electrodes in practice. Some seget capacitively coupled electrodes suffer from less skin-motion artifact noise than dry electrodes [1]. Moré detailed studies need to be conducted Assume 100mV 60Hz CM Interference, 1mV erting a layer of instation between the skin and electrode. From an electrical perspective, the high capacitance of the thin CMRR = 26dB: SNR = -14dB insulation layer is an effective short at signal frequencies and

have no effect on the signal quality vis-a-vis dry electrodes. One obvious downside, however, is that the insulated nature of the electrode precludes a frequency response down to DC, which may be important for certain applications.

CMRR = 104dB: SNR = 64dB (clinical grade)

CMRR = 64dB: SNR = 24dB

V. NON-CONTACT, CAPACITIVE ELECTRODES Wet and dry electrodes both require direct physical skin

CMRR, Interference Rejection drives input impedance need more than figure ight of electrode, can sense signals with an explicit gap between the Unfor

Challenges and Future Directions

Building Novel Sensor Systems

- Less need to focus on low-noise input amplifiers for most applications
- Opportunity to design very low-power, highly integrated systems
- Possible to make very inexpensive, ubiquitous sensors
- And/or place sensors in places that are currently impractical
- Major need for complete and integrated systems

Finding the Right Applications

- Medical market is conservative and very cost-conscious
- Many conventional technologies (e.g., sticky electrodes) are cheap, perform well and more than 'good-enough'
- Better to focus on new and underserved applications rather than trying to replace existing technology
- Need to tailor sensor/system design to specific application
- Don't forget the appearance, mechanics and user experience!