

Nonlinear Dynamics of Neural Firing

BENG/BGGN 260 Neurodynamics

University of California, San Diego

Week 3

Reading Materials

- E.M. Izhikevich, *Dynamical Systems in Neuroscience*, MIT Press, 2007, Ch. 1-2, pp. 53-121.
- C. Koch, *Biophysics of Computation*, Oxford Univ. Press, 1999, Ch. 7, pp. 172-192.

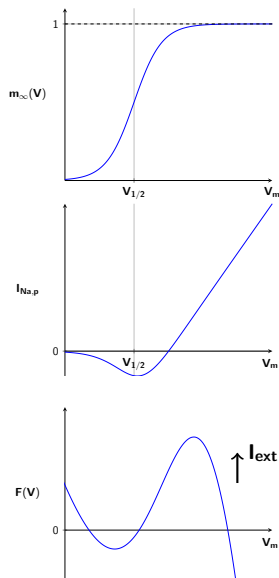
One Dimensional Systems

$$C_m \frac{dV_m}{dt} = I_{\text{ext}} - \underbrace{\bar{g}_{Na} m_{\infty}(V_m)(V_m - E_{Na})}_{I_{Na,p}} - g_L (V_m - E_L)$$

$I_{Na,p}$ persistent, fast Na^+ (Izh. p.55)

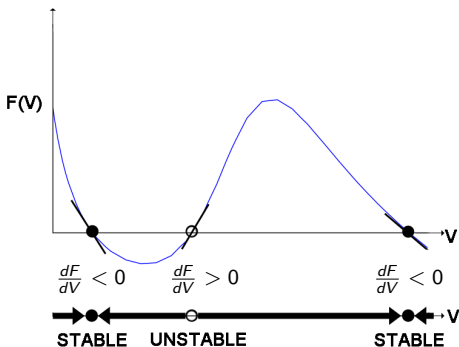
$$m_{\infty} = \frac{1}{1 + e^{-(V_m - V_{1/2})/k}}$$

$$\Rightarrow \frac{dV}{dt} = F(V)$$



Phase Portrait, Equilibria

$$\frac{dV}{dt} = F(V)$$



Small-signal analysis:

$$V = V_0 + \tilde{v}$$

$$\frac{d\tilde{v}}{dt} \approx \alpha \tilde{v} \quad \text{with} \quad \alpha = \left. \frac{dF}{dV} \right|_{V_0}$$

$$\tilde{v} \approx \tilde{v}_0 e^{+\alpha t} \quad \text{stable for } \alpha \leq 0 \text{ (decaying perturbation)}$$

Bistability and Hysteresis

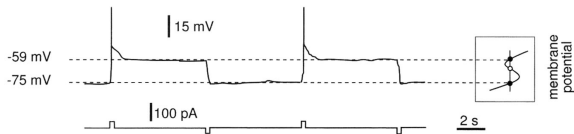


Figure 3.16: Membrane potential bistability in a cat TC neuron in the presence of ZD7288 (pharmacological blocker of I_h). (Modified from Fig. 6B of Hughes et. al. 1999).

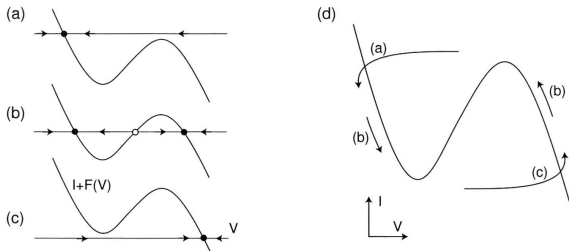


Figure 3.17: Bistability and hysteresis loop as I changes.

Saddle-Node Bifurcation

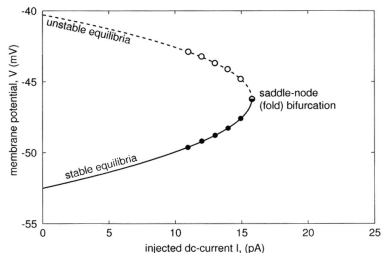
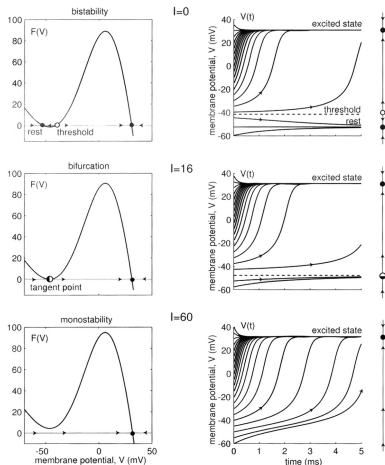


Figure 3.30 Bifurcation diagram of the system in Fig. 3.26.

Figure 3.25: Bifurcation in the $I_{Na,p}$ -model (3.5): The resting state and the threshold state coalesce and disappear when the parameter I increases.

Izhikevich, pg. 72, pg. 77

Two-Dimensional Systems

- **Morris-Lecar**

$$C_m \frac{dV_m}{dt} = I_{\text{ext}} - \underbrace{\bar{g}_K w}_{\substack{\downarrow \\ n \quad (n=w) \\ \downarrow \\ n^4}} (V - E_K) - \underbrace{\bar{g}_{Ca} m_\infty}_{\substack{\downarrow \\ Na \\ \downarrow \\ m_\infty^3 (1-n)}} (V) (V - \underbrace{E_{Ca}}_{\substack{\downarrow \\ Na}}) - g_L (V - E_L)$$

ML
↓
→ $I_{Na,p} + I_K$
↓
simplified HH

$$\frac{dw}{dt} = \frac{w_\infty(V_m) - w}{\tau_w(V_m)}$$

- **FitzHugh-Nagumo, etc.**

$$\Rightarrow \begin{cases} \frac{dV}{dt} = F(V, W) \\ \frac{dW}{dt} = G(V, W) \end{cases}$$

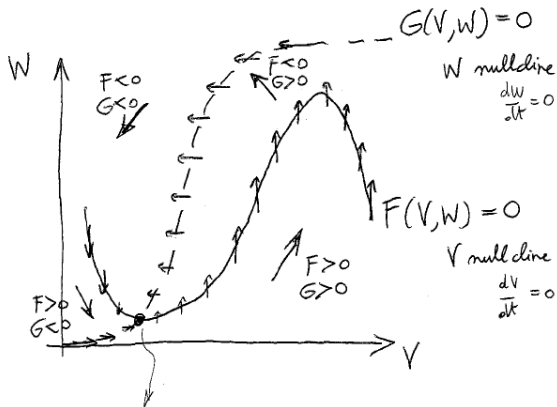
Dynamic repertoire:

- **Stationary Points**
- **Limit Cycles**
- **Stable Attractors**

No other limits in 2-D (since V and W are bounded)

Nullclines

$$\begin{cases} \frac{dV}{dt} = F(V, W) \\ \frac{dW}{dt} = G(V, W) \end{cases}$$



Equilibrium

- Stable \Rightarrow Stationary Point
- Unstable?

Stability

Equilibria:

$$\begin{cases} F(V_0, W_0) = 0 \\ G(V_0, W_0) = 0 \end{cases} \quad \text{intersection of nullclines}$$

Linear Analysis:

$$\begin{cases} V = V_0 + \tilde{v} \\ W = W_0 + \tilde{w} \end{cases}$$
$$\Rightarrow \begin{cases} \frac{d\tilde{v}}{dt} = a\tilde{v} + b\tilde{w} \\ \frac{d\tilde{w}}{dt} = c\tilde{v} + d\tilde{w} \end{cases} \quad \text{with} \quad \begin{matrix} a = \left. \frac{\partial F}{\partial V} \right|_{V_0, W_0} & b = \left. \frac{\partial F}{\partial W} \right|_{V_0, W_0} \\ c = \left. \frac{\partial G}{\partial V} \right|_{V_0, W_0} & d = \left. \frac{\partial G}{\partial W} \right|_{V_0, W_0} \end{matrix}$$

Eigenanalysis:

$$\mathbf{U} = \begin{pmatrix} \tilde{v} \\ \tilde{w} \end{pmatrix} \quad \overset{\text{Jacobian}}{\mathbf{A}} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$
$$\frac{d\mathbf{U}}{dt} = \mathbf{A}\mathbf{U}, \text{ or } \mathbf{U} = c_1\mathbf{U}_1e^{\lambda_1 t} + c_2\mathbf{U}_2e^{\lambda_2 t} \quad \text{with} \quad \begin{matrix} \mathbf{A}\mathbf{U}_1 = \lambda_1\mathbf{U}_1 \\ \mathbf{A}\mathbf{U}_2 = \lambda_2\mathbf{U}_2 \end{matrix}$$

eigenvectors eigenvalues

$$\begin{cases} \text{Re } \lambda_1 < 0 \text{ and } \text{Re } \lambda_2 < 0 & \Rightarrow \text{stable fixed point} \\ \text{Re } \lambda_1 > 0 \text{ or } \text{Re } \lambda_2 > 0 & \Rightarrow \text{unstable} \end{cases}$$

Stability (Continued)

Eigenanalysis:

$$\mathbf{A}\mathbf{U} = \lambda\mathbf{U}$$

$$\det(\mathbf{A} - \lambda\mathbf{I}) = 0$$

$$\begin{vmatrix} a - \lambda & b \\ c & d - \lambda \end{vmatrix} = 0$$

$$\lambda^2 - \tau\lambda + \Delta = 0 \quad \text{with} \quad \begin{cases} \tau & = a + d & : \text{Trace}(\mathbf{A}) \\ \Delta & = ad - bc & : \det(\mathbf{A}) \end{cases}$$

$$\lambda_{1,2} = \frac{\tau \pm \sqrt{\tau^2 - 4\Delta}}{2}$$

$$\Rightarrow \begin{cases} \tau^2 > 4\Delta : \text{real, distinct eigenvalues} \\ \tau^2 = 4\Delta : \text{real, repeated eigenvalues} \\ \tau^2 < 4\Delta : \text{complex conjugate eigenvalues} \end{cases}$$

Stability of 2-D Equilibria

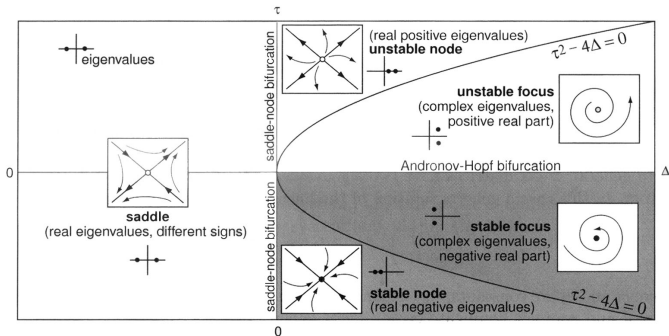


Figure 4.15: Classification of equilibria according to the trace (τ) and the determinant (Δ) of the Jacobian matrix \mathbf{A} . The shaded region corresponds to stable equilibria.

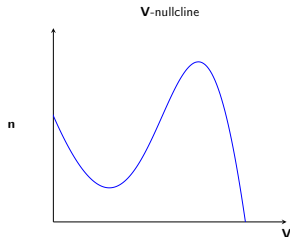
Izhikevich, pg. 104

Morris-Lecar and $I_{Na,p} + I_K$

Persistent sodium and potassium ($I_{Na,p} + I_K$) is equivalent to Morris-Lecar ($n = w$).

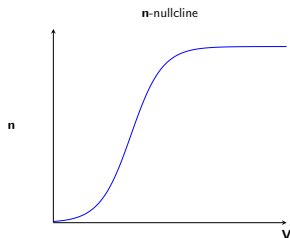
V – nullcline :

$$F(V, n) = \frac{1}{C} \left(I_{ext} - \bar{g}_K n (V - E_K) - \bar{g}_{Na} m_{\infty}(V) (V - E_{Na}) - g_L (V - E_L) \right) = 0 \Rightarrow$$
$$n = \frac{I_{ext} - \bar{g}_{Na} m_{\infty}(V) (V - E_{Na}) - g_L (V - E_L)}{\bar{g}_K (V - E_K)}$$



n – nullcline :

$$G(V, n) = \frac{n_{\infty}(V) - n}{\tau_n(V)} = 0 \Rightarrow$$
$$n = n_{\infty}(V)$$



$I_{Na,p} + I_K$ (or ML) Nullclines

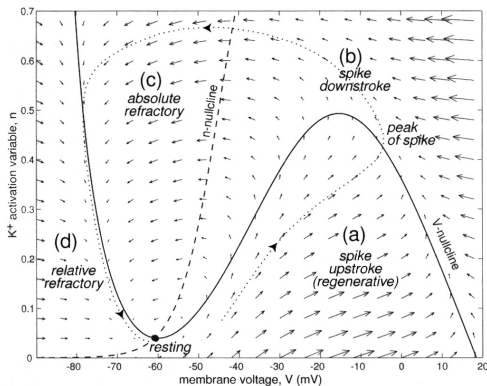


Figure 4.4: Nullclines of the $I_{Na,p} + I_K$ -model (4.1, 4.2) with low-threshold K^+ current in Fig. 4.1b. (The vector field is slightly distorted for the sake of clarity of illustration).

Izhikevich, pg. 93

Graded Action Potentials

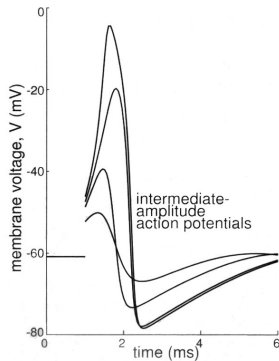
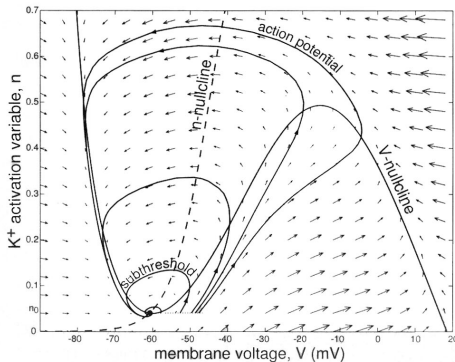


Figure 4.7: Failure to generate all-or-none action potentials in the $I_{Na,p} + I_K$ -model.

Izhikevich, pg. 95

Variable Threshold

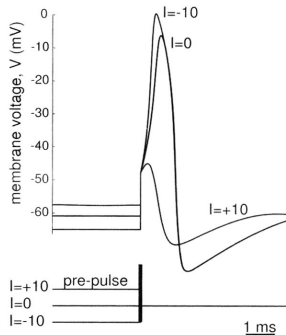
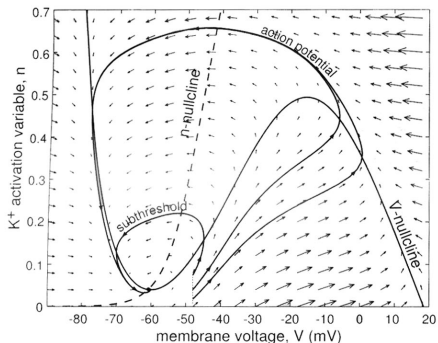


Figure 4.8: Failure to have a fixed value of threshold voltage in the $I_{Na,p} + I_K$ -model.

Izhikevich, pg. 96

Stable Limit Cycle

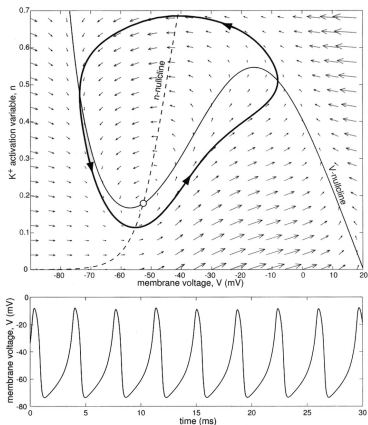


Figure 4.10: Stable limit cycle in the $I_{Na,p} + I_K$ -model (4.1, 4.2) with low-threshold K^+ current and $I = 40$.