

## Lecture 3

# Basic Sensors: Displacement, Strain, and Pressure

### References

Webster, Ch. 2 (Sec. 2.1-2.4).

<http://en.wikipedia.org/wiki/Potentiometer>

[http://en.wikipedia.org/wiki/Strain\\_gauge](http://en.wikipedia.org/wiki/Strain_gauge)

[http://en.wikipedia.org/wiki/Wheatstone\\_bridge](http://en.wikipedia.org/wiki/Wheatstone_bridge)

# BASIC SENSORS

Webster, Chap. 2

A sensor is a type of transducer: it converts a physical parameter into an electrical signal.

Here we will first consider:

- Physical parameters:

- DISPLACEMENT: main parameter used to measure STRAIN, ACCELERATION, FORCE, STRESS, PRESSURE, etc.

- TEMPERATURE

- Electrical signals:

- VOLTAGE or CHARGE, directly transduced

- IMPEDANCE:

R: resistive sensor

L: inductive sensor

C: capacitive sensor

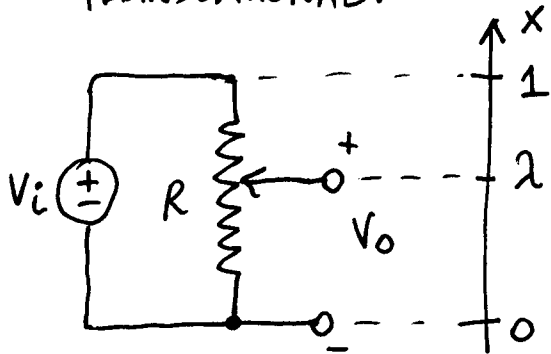
indirectly transduced to VOLTAGE through

~ VOLTAGE DIVIDER or a WHEATSTONE BRIDGE.

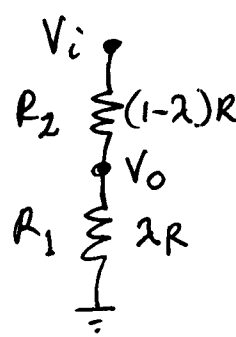
# - Resistive displacement sensors

- Potentiometer : a voltage divider which transduces position into voltage through a ratio of resistances:

## - TRANSLATIONAL:



linear displacement,  $0 \leq \lambda \leq 1$



$$V_o = \frac{R_1}{R_1 + R_2} V_i$$

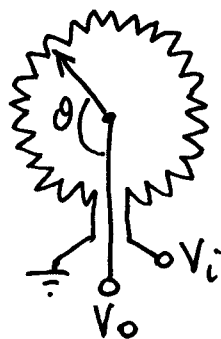
$$R_1 = \lambda R$$

$$R_2 = (1 - \lambda)R$$

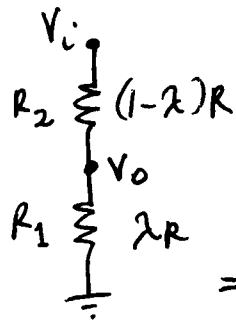
$$\Rightarrow V_o = \lambda \cdot V_i$$

↓ VOLTAGE OUTPUT  
↓ TRANSLATION

## - SINGLE TURN:



angular displacement,  
 $\theta_{min} \leq \theta \leq \theta_{max}$



$$\text{where } \lambda = \frac{\theta - \theta_{min}}{\theta_{max} - \theta_{min}}$$

$$\Rightarrow V_o = \frac{\theta - \theta_{min}}{\theta_{max} - \theta_{min}} \cdot V_i$$

↓ VOLTAGE OUTPUT  
↓ RELATIVE TURN

typically  $\theta_{min}$  : close to 0

$\theta_{max}$  : close to  $2\pi$  ( $360^\circ$ )

## - MULTITURN : N windings $\Rightarrow$

$\theta_{min}$  : close to 0

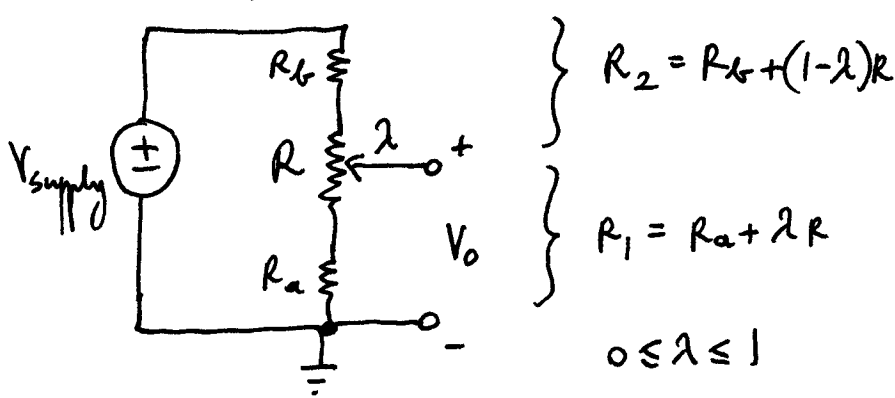
$\theta_{max}$  : close to  $2\pi N$  ( $360^\circ \times N$ )

NOTE:

Typically,  $V_i$  is a supply voltage  $V_{supply}$ , such as a battery.  
The output  $V_o$  then ranges between GND (0V) and  $V_{supply}$ .

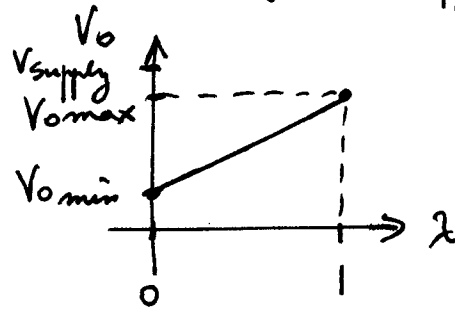
Problem: some signal processing circuits can't handle inputs close to the power supply rails (GND and  $V_{supply}$ ), so that small and large displacements  $\lambda$  (turns) may be cut off.

Solution: add series resistors between the supplies and the potentiometer:



$$V_o = \frac{R_1}{R_1 + R_2} \cdot V_{supply}$$

$$\Downarrow$$
$$V_o = \frac{R_a + \lambda R}{R_a + R_b + R} \cdot V_{supply}$$



Example:  $V_{supply} = 5V$   
 $R = 10k\Omega$

Choose  $R_a$  and  $R_b$  such that the output range is  $1V \leq V_o \leq 4V$  (1V of margin on both sides).

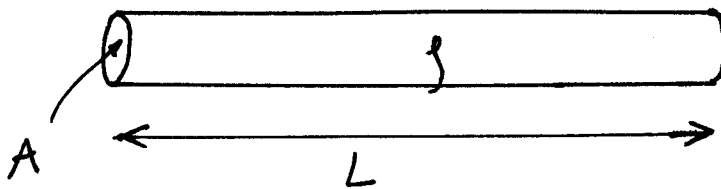
$$V_{o\min} = \frac{R_a}{R_a + R_b + R} \cdot V_{supply}$$

$$V_{o\max} = \frac{R_a + R}{R_a + R_b + R} \cdot V_{supply}$$

$$\rightarrow R_a = R_b = \frac{R}{3} = 3.33k\Omega$$

— Strain gauge (or "gauge") : more sensitive for very small displacements

Wire resistance depends on geometry that changes with STRAIN



$\rho$ : resistivity [ $\Omega \cdot m$ ]

Resistance :  $R = \rho \cdot \frac{L}{A}$  depends on  $\begin{cases} \text{MATERIAL } (\rho) \\ \text{GEOMETRY } (L, A) \end{cases}$

A very small change in length  $L \rightarrow L + dL$  results in a change in resistivity  $\rho \rightarrow \rho + d\rho$  and area  $A \rightarrow A + dA$ , which combine into a change in resistance  $R \rightarrow R + dR$ :

$$dR = \frac{\rho}{A} dL - \frac{\rho L}{A^2} dA + \frac{L}{A} d\rho, \text{ or:}$$

$$\frac{dR}{R} = \frac{dL}{L} - \frac{dA}{A} + \frac{d\rho}{\rho}$$

Poisson's ratio relates change in diameter to change in length:

$$\frac{dD}{D} = -\mu \cdot \frac{dL}{L} \quad \text{where} \quad A = \frac{\pi D^2}{4}, \text{ or } \frac{dA}{A} = 2 \frac{dD}{D}$$

POISSON'S  
RATIO  
( $\approx 0.3$   
for metals)

$$\Rightarrow \frac{dA}{A} = -2\mu \cdot \frac{dL}{L}$$

$$\Rightarrow \frac{dR}{R} = \underbrace{(1 + 2\mu)}_{\text{DIMENSIONAL EFFECT}} \cdot \frac{dL}{L} + \underbrace{\frac{d\rho}{\rho}}_{\text{PIEZO-RESISTIVE EFFECT}}$$

Gauge factor ("gauge" factor)  $G$ : ratio of (small) relative changes in resistance and length:

$$G \stackrel{\text{def.}}{=} \frac{\Delta R/R}{\Delta L/L} = 1 + 2\mu + \frac{\Delta \rho/\rho}{\Delta L/L} \quad (\Delta L/L \ll 1)$$

depends on the material:

- metals:  $\Delta \rho/\rho \approx 0$  and  $\mu \approx 0.5 \Rightarrow G \approx 2$
- semiconductors:  $\Delta \rho/\rho / \Delta L/L \approx \pm 100 \Rightarrow G \approx \pm 100$ , but temperature sensitive  $\Rightarrow$  requires temperature compensation such as in a bridge.

NOTE: Several measurands fit the displacement category:

- STRAIN:  $\epsilon \stackrel{\text{def.}}{=} \frac{\Delta L}{L} \Rightarrow \frac{\Delta R}{R} = G \cdot \epsilon$

- STRESS:  $\sigma \stackrel{\text{def.}}{=} \frac{F}{A}$  force per unit area

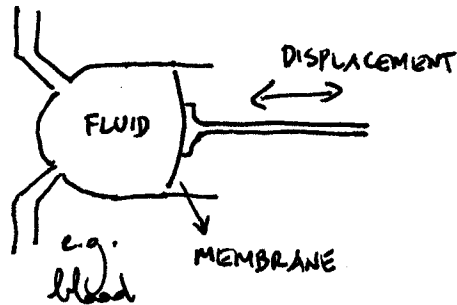
Young's Modulus:  $E = \frac{\sigma}{\epsilon} = \frac{F/A}{\Delta L/L}$  depends on the material

$$\Rightarrow \frac{\Delta R}{R} = G \cdot \epsilon = \frac{G}{E} \cdot \sigma$$

- PRESSURE: like stress, but for fluids etc...

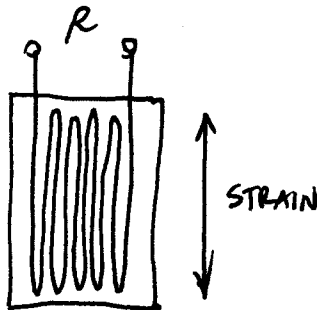
# Physical strain gauge:

- unbonded, e.g.: pressure sensor



- fluid pressure
- membrane displacement
- wire elongation
- resistance change

- bonded



wire on film/foil substrate which is conformal to host surface and hence directly measures its strain.

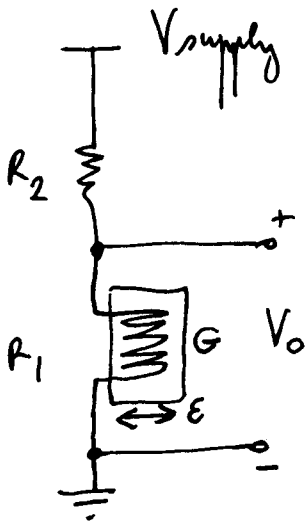
$N$  turns

- $N$  times greater resistance  $R$
- $N$  times greater sensitivity  $\Delta R/\epsilon$

- typically embedded in a voltage divider, or a differential voltage divider (Wheatstone bridge), ideally with temperature compensation.

It is best to match resistance values and their temperature coefficients, at least in pairs.

Example: Voltage divider structure with single strain gauge:



$$V_0 = \frac{R_1}{R_1 + R_2} \cdot V_{\text{supply}}$$

$$dV_0 = \left( \frac{dR_1}{R_1 + R_2} - \frac{R_1}{(R_1 + R_2)^2} \cdot dR_1 \right) V_{\text{supply}}$$

$$= \frac{R_2 \cdot dR_1}{(R_1 + R_2)^2} \cdot V_{\text{supply}}$$

where  $dR_1 = G \cdot \epsilon \cdot R_1$

$$\Rightarrow dV_0 = \frac{R_1 R_2}{(R_1 + R_2)^2} \cdot G \cdot \epsilon \cdot V_{\text{supply}}$$

$$\Rightarrow \text{Sensitivity: } \frac{dV_0}{\epsilon} = \frac{R_1 R_2}{(R_1 + R_2)^2} \cdot G \cdot V_{\text{supply}}$$

- Find  $R_2$  to maximize sensitivity

$$\Rightarrow R_2 = R_1 \quad \Rightarrow \frac{R_1 R_2}{(R_1 + R_2)^2} = \frac{1}{4}$$

- What is the temperature coefficient if  $R_1$  and  $R_2$  have identical temperature coefficients?

$$R_1 \rightarrow (1 + \alpha \Delta T) R_1$$

$$R_2 \rightarrow (1 + \alpha \Delta T) R_2$$

$$\Rightarrow \frac{R_1 R_2}{(R_1 + R_2)^2} \rightarrow \frac{(1 + \alpha \Delta T)^2}{(1 + \alpha \Delta T)^2} \cdot \frac{R_1 R_2}{(R_1 + R_2)^2}$$

$\Rightarrow$  zero temperature coefficient in the sensitivity

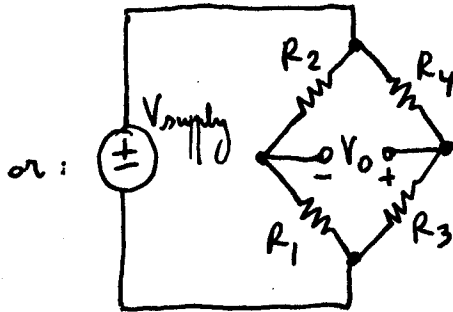
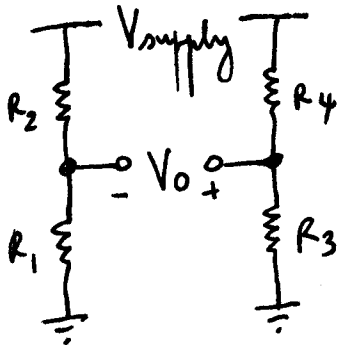
$\rightarrow$  TEMPERATURE COMPENSATED SENSITIVITY



# WHEATSTONE BRIDGE (or "bridge" for short):

Differential combination of two voltage dividers

- linear
- zero offset
- high sensitivity
- Temp. compensated



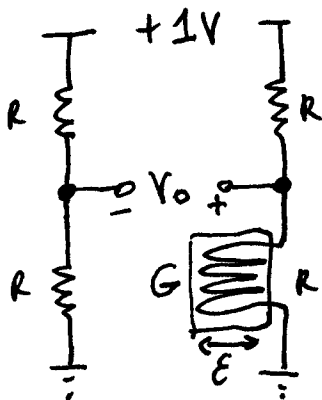
$$\Rightarrow V_0 = \left( \frac{R_3}{R_3 + R_4} - \frac{R_1}{R_1 + R_2} \right) V_{\text{supply}}$$

or  $V_0 = 0$  for  $\frac{R_1}{R_2} = \frac{R_3}{R_4}$  (balanced)

Ideally  $R_1 = R_2 = R_3 = R_4$  for maximum sensitivity.

Any of  $R_1, R_2, R_3, R_4$  or their combinations can be strain gauges, ideally differentially matched in pairs.

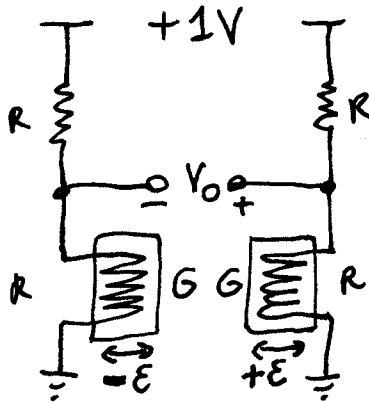
## Examples:



⇒ SENSITIVITY:

$$\frac{V_0}{\epsilon} = \frac{1}{4} G \cdot 1V$$

→ LOWEST  
not T comp.

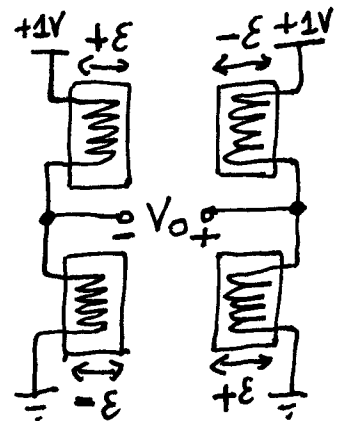


differentially activated  
(one pulls, the other pushes)

⇒ SENSITIVITY:

$$\frac{V_0}{\epsilon} = \frac{1}{2} G \cdot 1V$$

T comp.

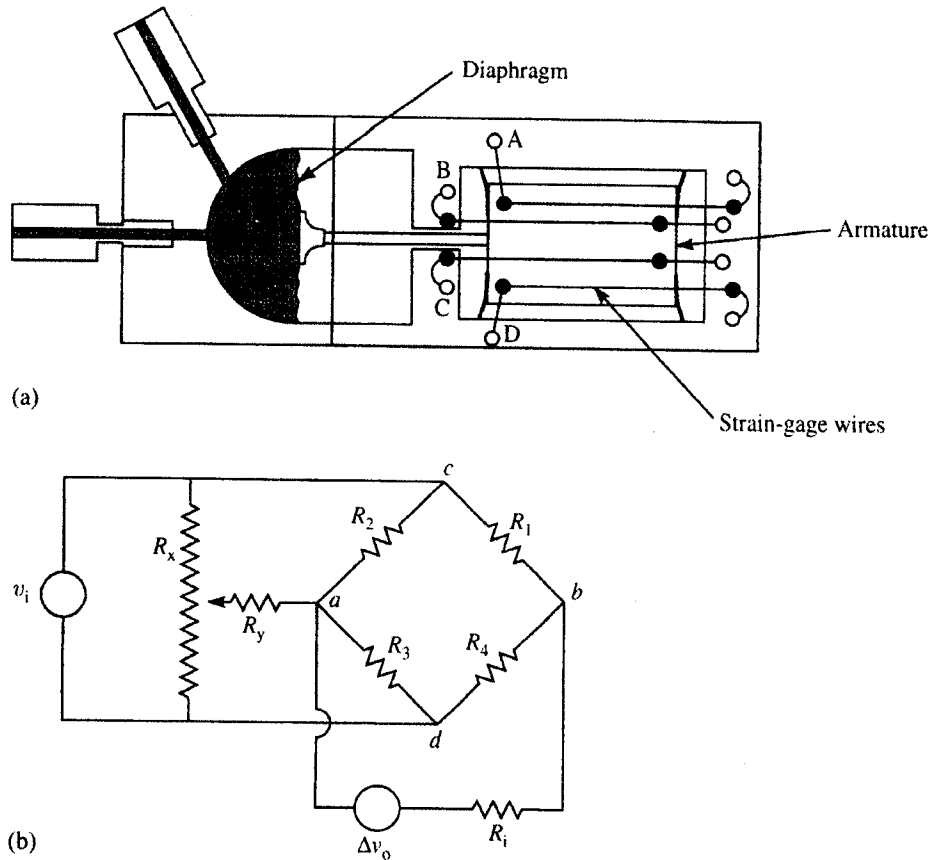


double differentially activated

⇒ SENSITIVITY:

$$\frac{V_0}{\epsilon} = G \cdot 1V$$

→ HIGHEST  
T comp.



**Figure 2.2** (a) Unbonded strain-gage pressure sensor. The diaphragm is directly coupled by an armature to an unbonded strain-gage system. With increasing pressure, the strain on gage pair B and C is increased, while that on gage pair A and D is decreased. (b) Wheatstone bridge with four active elements:  $R_1 = B$ ,  $R_2 = A$ ,  $R_3 = D$ , and  $R_4 = C$  when the unbonded strain gage is connected for translational motion. Resistor  $R_y$  and potentiometer  $R_x$  are used to initially balance the bridge,  $v_i$  is the applied voltage, and  $\Delta v_o$  is the output voltage on a voltmeter or similar device with an internal resistance of  $R_i$ .