Review 2: Practice Quiz 2

Quiz 2 covers all material, as covered in Lectures 8 through 11, and Homework 4 and 5. It is open book, open notes, and online, but web search is prohibited. *No collaboration or communication in any form is allowed*, except for questions to the instructor and TAs.

Quiz 2 will be posted online, and is due over Canvas as scheduled. Do not discuss any class-related topics among yourselves before or after you have completed your quiz, and until the submission deadline has passed.

References

Tranquillo JV. *Biomedical Signals and Systems*, Morgan & Claypool Publishers, Dec. 2013. Ch. 8, Ch. 9, Ch. 11.

PRACTICE QUIZ

Problem 1

Consider the following linear time-invariant (LTI) biosystem:

$$H(s) = \frac{10 s + 1}{s^2 + 11 s + 10}$$

- 1. Sketch the Bode plot.
- 2. Find the closed-loop DC error, and phase margin, for proportional control with 20 dB gain.

- control with 20 dB gain.
- 3. Now add integral control, keeping the proportional control with 20 dB gain. Maximize the value of integral gain to maintain the same value of phase margin as without integral control. Find the closed-loop DC error.
- 4. Find the closed-loop transfer function for these values of proportional and integral gain, and sketch the Bode plot. Validate that the closed-loop DC error and high-frequency dynamics are consistent with those predicted by the above open-loop analysis.
- 5. Is it helpful to add derivative control for this biosystem? Explain.

Problem 2

Here we consider the dynamics of a coupled set of three ordinary differential equations describing population dynamics of three interacting species x_1 , x_2 and x_3 :

$$\frac{d \times_{1}}{dt} = -\forall \times_{3}$$

$$\frac{d \times_{2}}{dt} = -\forall \times_{1} \qquad (\forall > \circ)$$

$$\frac{d \times_{3}}{dt} = -\forall \times_{2}$$

- Show a block diagram of this closed-loop system interconnecting three blocks: a "controller" generating x₁ from x₃ and zero target; a "plant" generating x₂ from x₁; and a "measurement system" generating x₃ from x₂.
- 2. Find the open-loop transfer function, and find the phase margin. What does it imply about the stability of the closed-loop system?
- 3. Find the closed-loop transfer function, and find the poles. Is the system stable or unstable, and in what form? Check the consistency of

- 2. Find the open-loop transfer function, and find the phase margin. What does it imply about the stability of the closed-loop system?
- 3. Find the closed-loop transfer function, and find the poles. Is the system stable or unstable, and in what form? Check the consistency of your answer with the above open-loop analysis.

Problem 3

- 1. Find an expression for the closed-loop gain $A_{CL}(\omega)$ as a function of the open-loop gain $A_{OL}(\omega)$ and the open-loop phase $\mathcal{Y}_{OL}(\omega)$.
- 2. Validate that for zero phase margin, the closed-loop gain goes to infinity. Explain why.
- 3. Show that for small values of phase margin, the closed-loop gain at resonance is approximately given by the reciprocal of the phase margin (in radians):

$$A_{CL}(\omega_{res}) \approx \frac{1}{\varphi_{oL}(\omega_{res}) + \pi}$$

where ω_{res} is the resonant frequency at which $A_{OL}(\omega_{res}) = 1$.