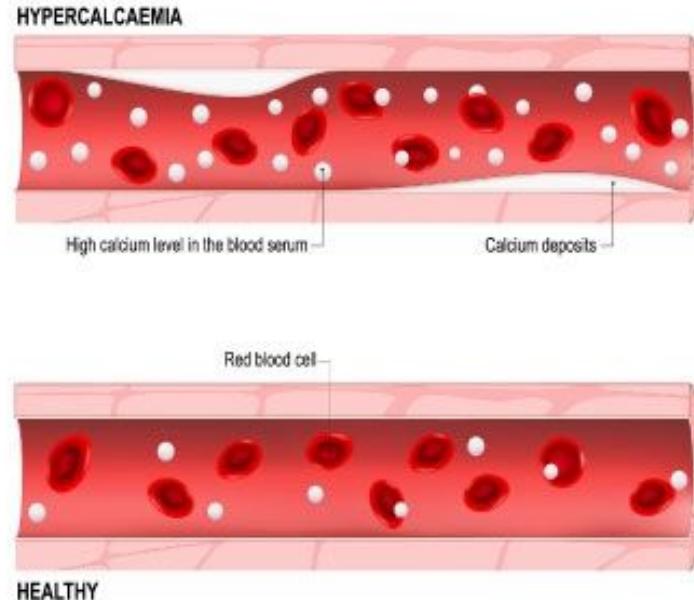


Calcitonin Regulation of Elevated Blood Calcium Levels

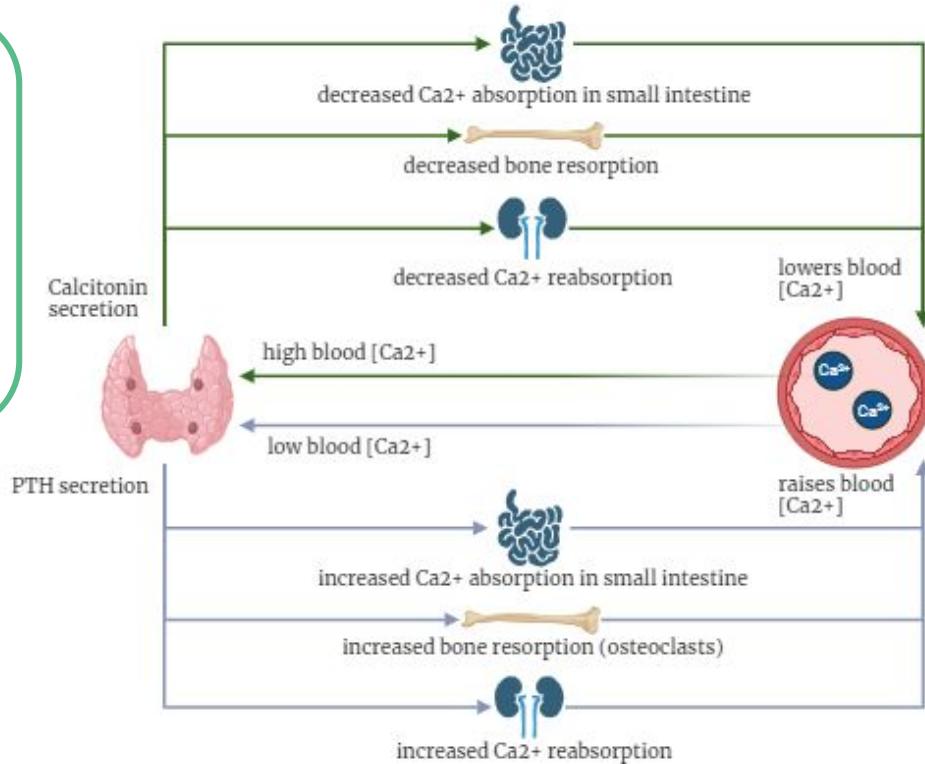
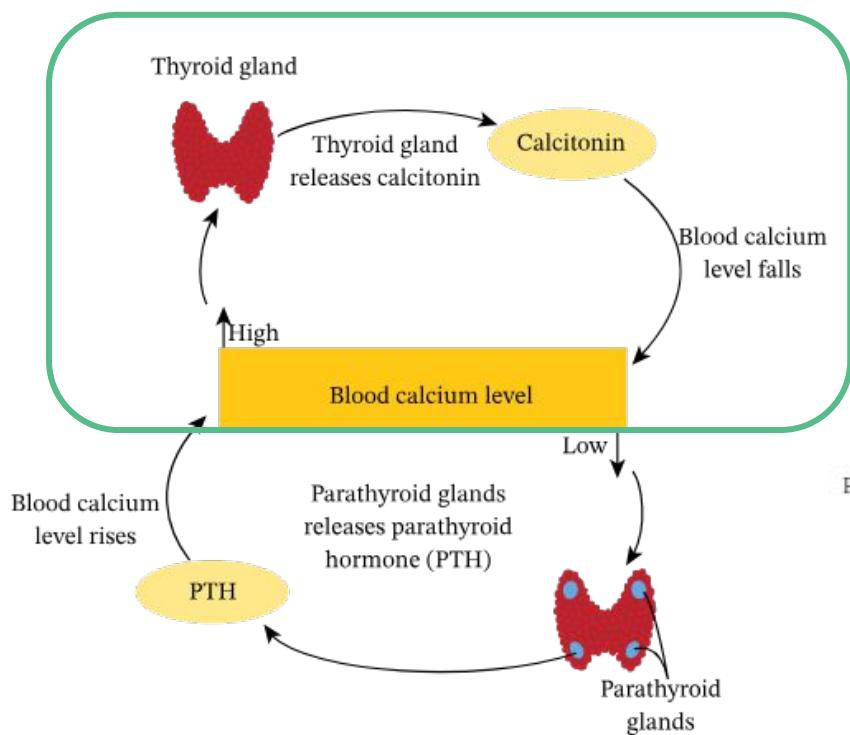
Megan Wu, Armando Ramil, Jacob Orozco, Mason Faust,
Millicent Salvino

Calcitonin

- Hormone produced by thyroid gland in response to *elevated blood calcium levels*
- Stimulated by calcium-sensing receptors (CaSR) in the parathyroid gland and kidney
- Blocks osteoclast activity to reduce bone resorption
- Decreases calcium reabsorption in the kidneys



Calcium Regulation



Goal & Assumptions

Model the calcitonin response to elevated calcium blood concentration.

1. The scope of the biosystem is limited to calcitonin and parathyroid hormone
2. This model only considers calcium concentrations in the blood
3. The effect of PTH is constant and does not change as a function of the calcium concentration since we are modeling the response to elevated calcium where calcitonin is assumed to have a more significant effect
4. The initial concentrations of calcitonin and calcium are the concentrations at time zero
5. Calcitonin feedback is modeled using a PD controller

Parameters & ODEs

Nonlinear Ordinary Differential Equations:

$$\frac{dc}{dt} = -kC(t)N(t) + \frac{1}{\tau_1}C(t) \quad (1)$$

$$\frac{dN}{dt} = \alpha I(t) - \frac{1}{\tau_2}N(t) \quad (2)$$

$$I(t) = K_p e(t) + K_i \int_{-\infty}^t e(t) dt + K_d \frac{d}{dt} e(t) \quad (3)$$

$$e(t) = C_{meas} - T \quad (4)$$

Variable	Value	Units
k	0.3	L/min*mmol
τ_1	276	min
τ_2	1642	min
α	0.20	1/L
T	2.1	mmol/L

C(t) [mmol/L] = calcium concentration

N(t) [mmol/L] = calcitonin concentration

Open Loop Transfer Function

Linearized Ordinary Differential Equations:

$$C(s) = \frac{2kN_o C_o - kC_o N(s) + C_o (1 - \frac{1}{\tau_1})}{s + kN_o - \frac{1}{\tau_1}} \quad ; \quad N(s) = \frac{\alpha I(s) + N_o}{s + \frac{1}{\tau_2}}$$

$$H(s) = \frac{-kC_o \alpha}{s^2 + s(kN_o - \frac{1}{\tau_1} + \frac{1}{\tau_2}) + (\frac{kN_o}{\tau_2} - \frac{1}{\tau_2 \tau_1})}$$

where $k_1 = 0.3$, $C_o = 2.5 \frac{mmol}{L}$, $N_o = 2.0482 * 10^{-9} \frac{mmol}{L}$,

$$\tau_1 = 4.6 \text{ hr}, \tau_2 = 23.4 \text{ hr}, \alpha = 0.2 \frac{1}{L}$$

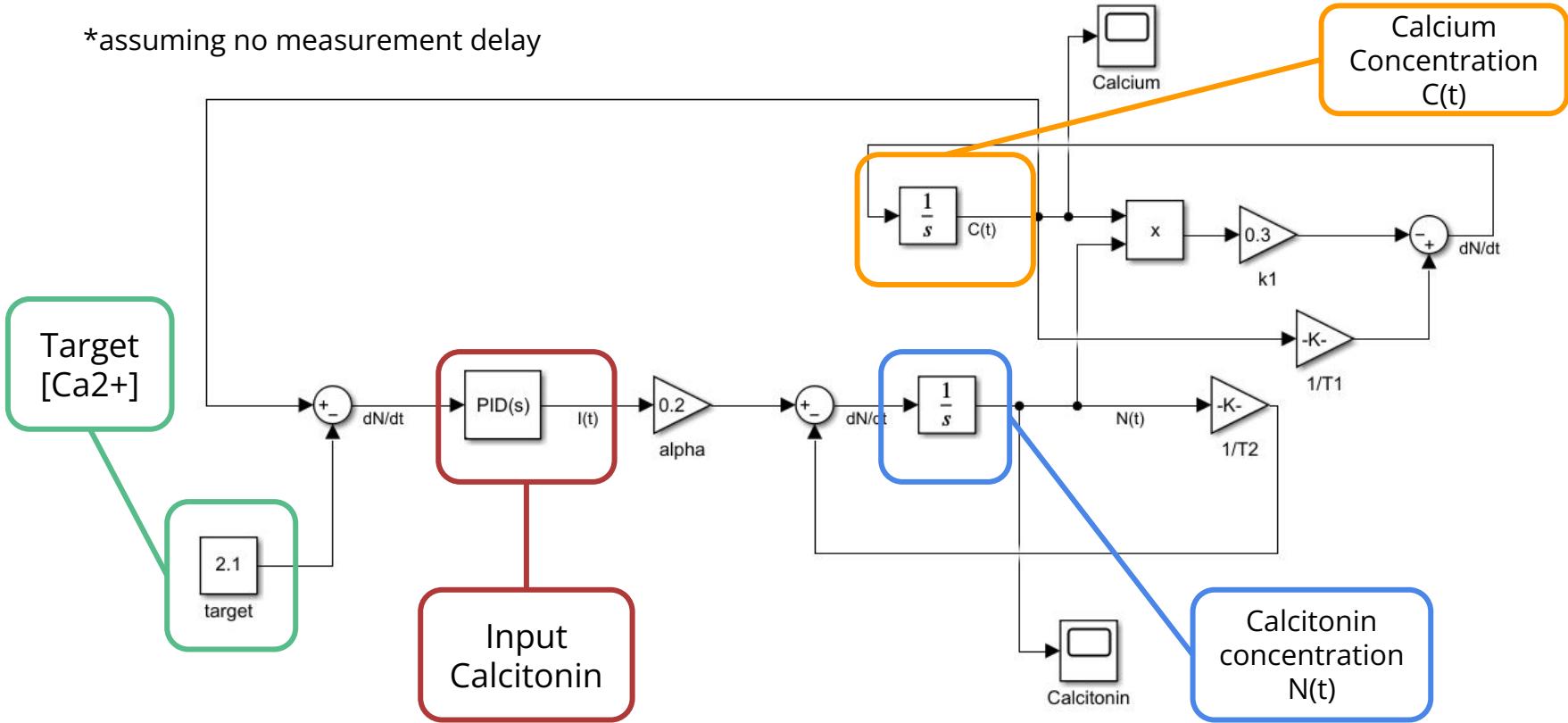
→ $H(s) = \frac{-0.15}{s^2 - 0.003014s - 2.207 \times 10^{-6}}$

Poles:

$$s = 0.00362, -0.000609$$

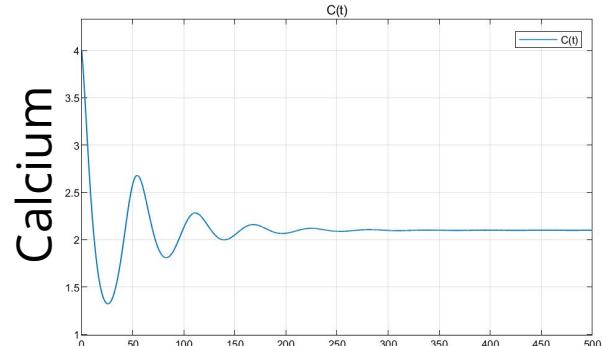
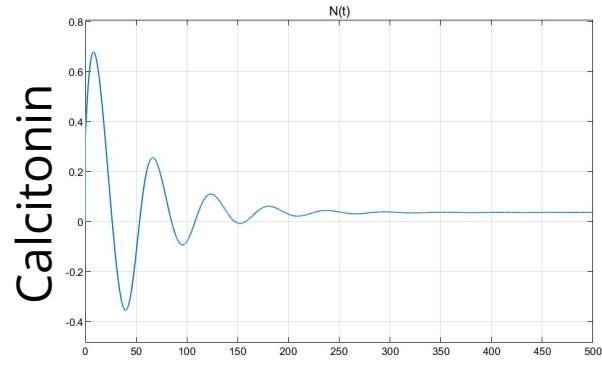
Block Diagram in Time Domain

*assuming no measurement delay

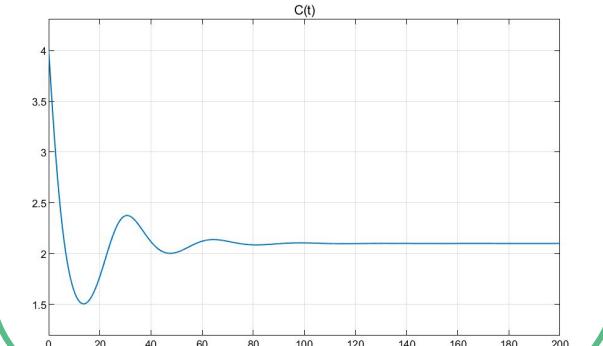
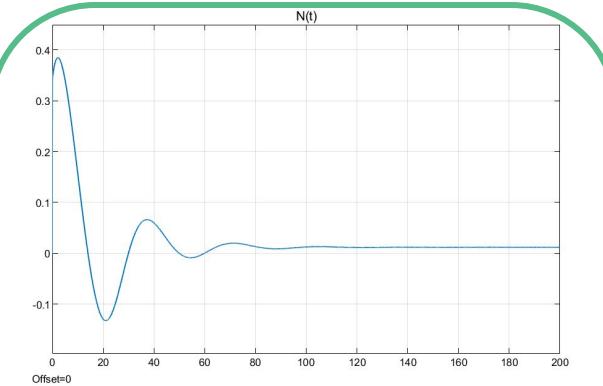


Sensitivity Analysis

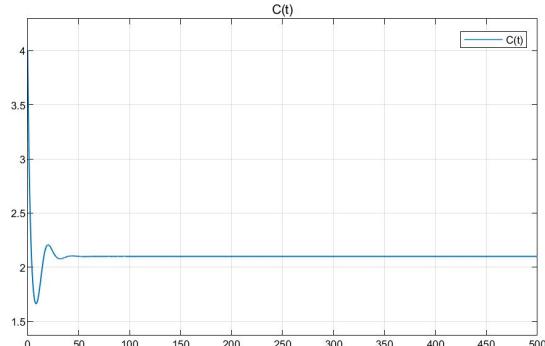
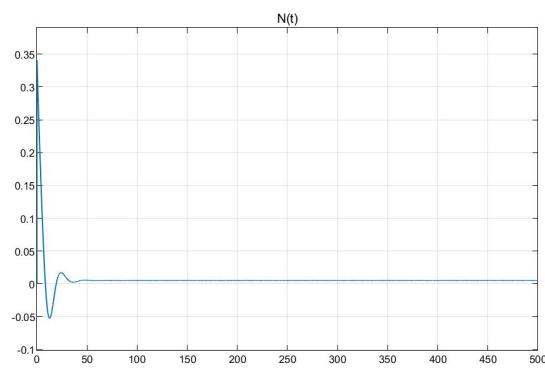
$k = 0.1$



$k = 0.3$

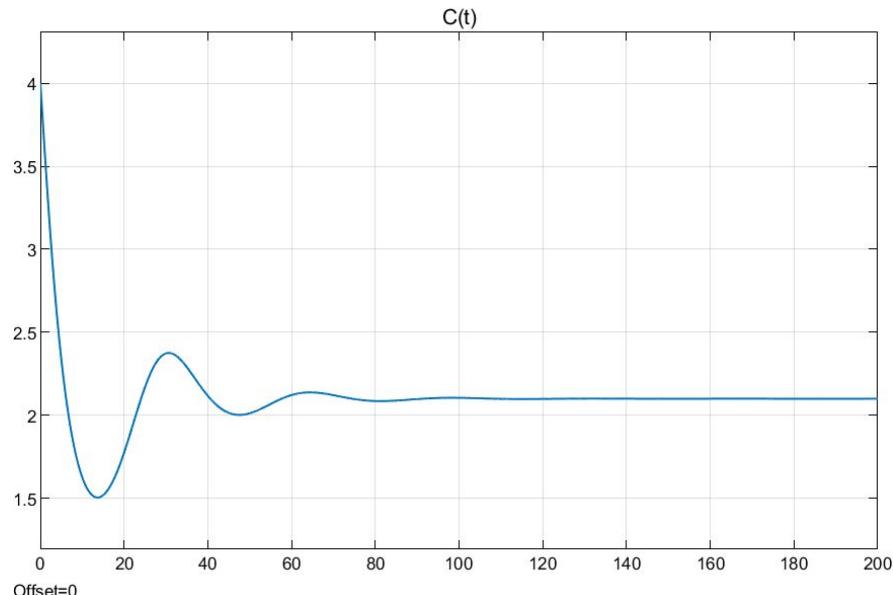


$k = 0.7$

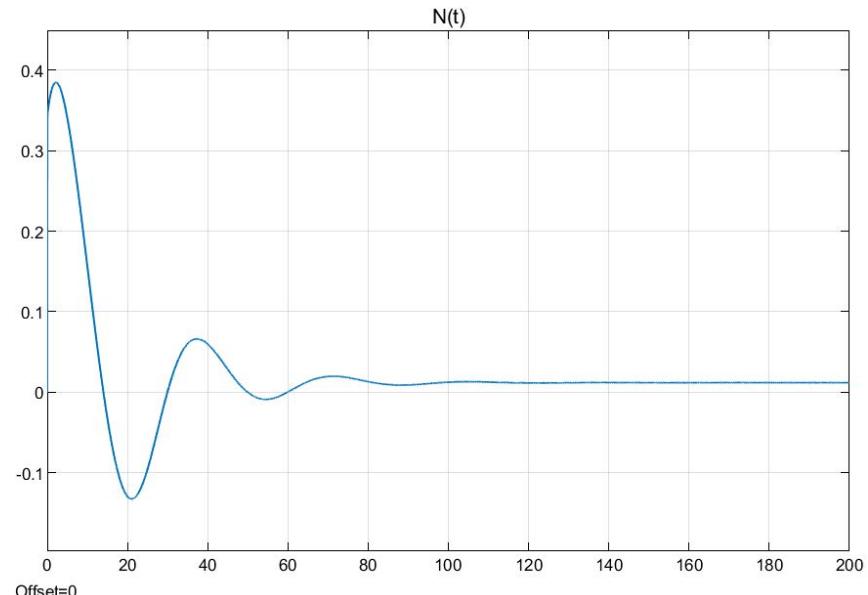


Output Response

Kd	0.3 L/min
Ki	0 L/min ²
Kp	0.9 L



Calcium Concentration

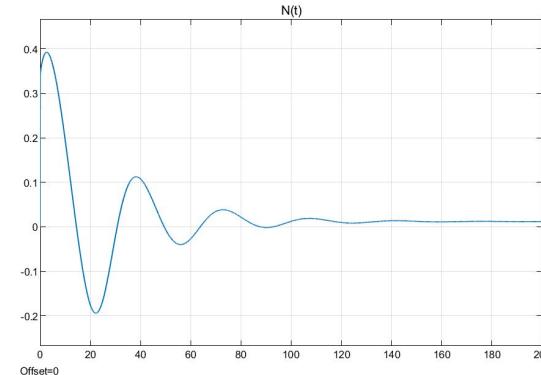
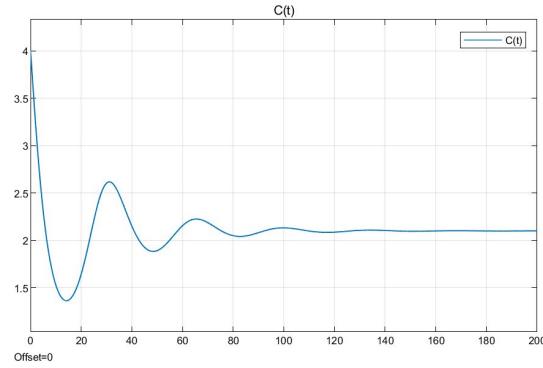


Calcitonin Concentration

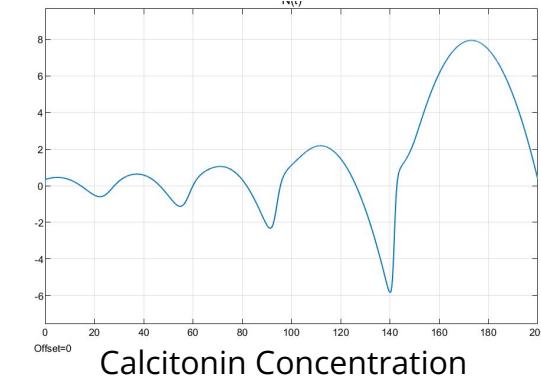
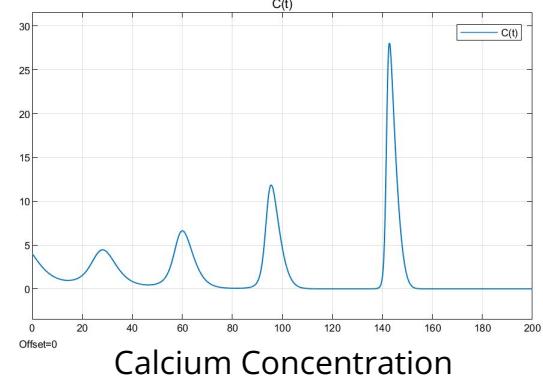
Output Response

*Adding integral control does not appear to improve the system response

Kd	0.3 L/min
Ki	0.01 L/min²
Kp	0.9 L



Kd	0.3 L/min
Ki	0.05 L/min²
Kp	0.9 L

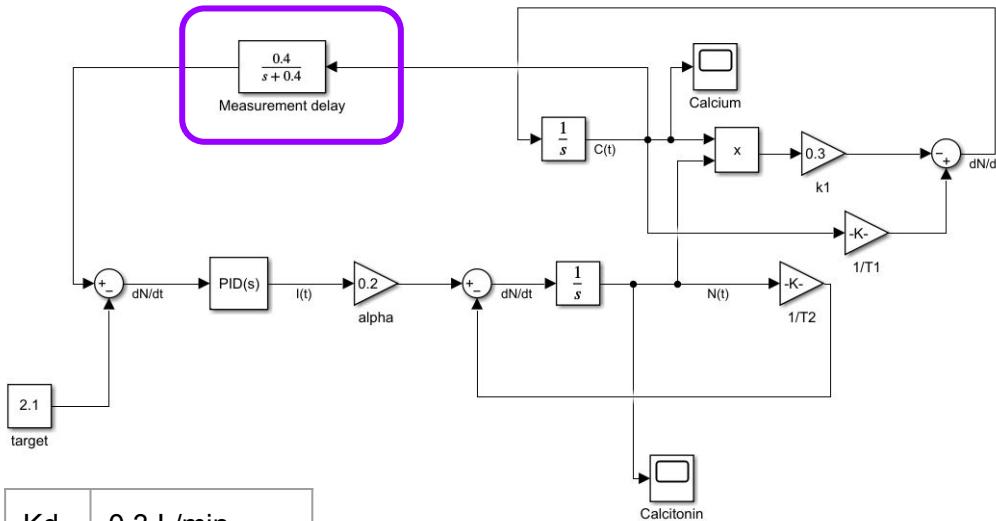


Calcium Concentration

Calcitonin Concentration

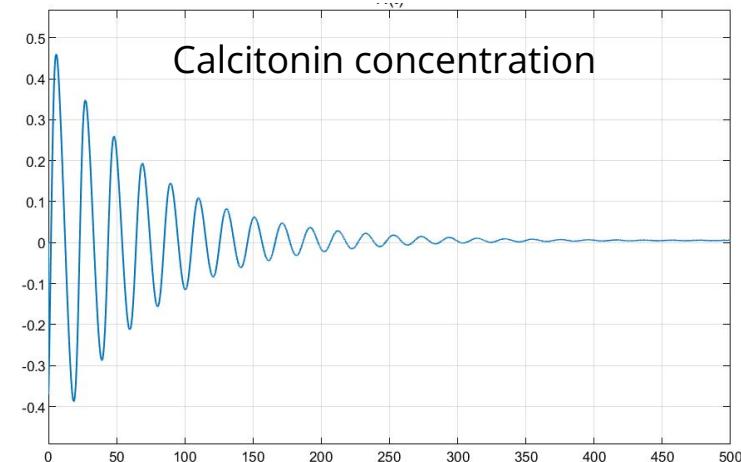
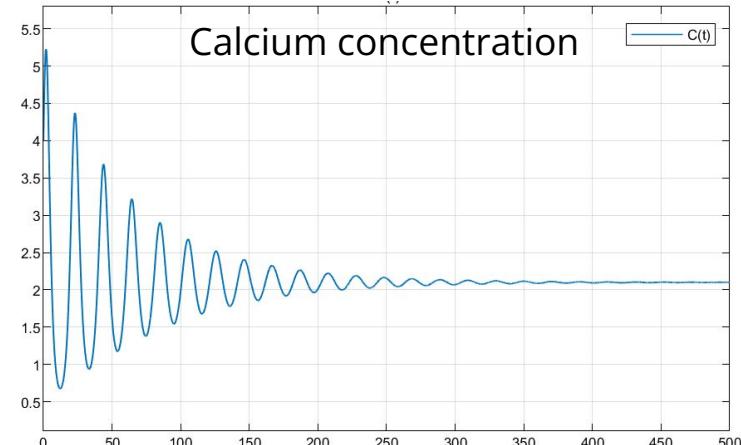
Adding a Measurement Delay

* Considering measurement delay of ~2.5 minutes



Kd	0.3 L/min
Ki	0 L/min ²
Kp	0.9 L

$$\frac{dC_{meas}}{dt} = \frac{1}{\tau_{meas}} (C(t) - C_{meas}(t)) \quad (5)$$



Closed Loop Transfer Function

Open loop transfer function

$$H(s) = \frac{-0.15}{s^2 - 0.003014s - 2.207 \times 10^{-6}}$$

Measurement Delay

$$G(s) = \frac{0.4}{s + 0.4}$$

Controller

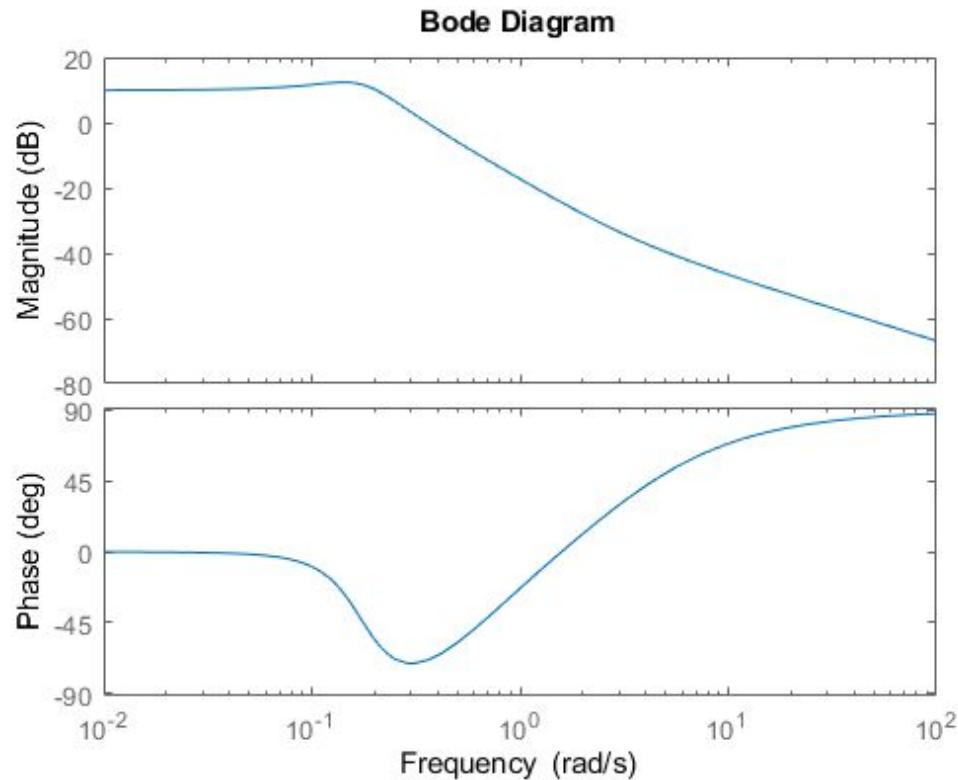
$$F(s) = K_p + K_d s = 0.9 + 0.3s$$

Closed loop transfer function

$$CL(s) = \frac{F(s)H(s)}{1 + G(s)F(s)H(s)} \longrightarrow CL(s) = \frac{-0.045s^2 - 0.153s - 0.054}{s^3 - 0.403s^2 - 0.0528s - 0.0172}$$

BODE Plot of Closed Loop System

- System response is stable until 10^{-1} rad/sec
- Downward slope indicates the attenuation of the system at higher frequencies
- Phase shift occurs when response becomes *unstable*



Limitations and Future Design Goals

- Our system only focused on the changes of calcitonin levels in the blood, in the future we could also model parathyroid mechanics which would increase calcium concentration in the blood.
- Manipulating the constants inputted in the transfer functions (ie. k variable) would provide a more stable system

Acknowledgements



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