## THE NEUROMORPHIC ENGINEER VOLUME 1, NUMBER 1 SPRING 2004

Beyond address-event communication: dynamicallyreconfigurable spiking neural systems

Large-scale artificial sensory information-processing systems that emulate biological intelligence when interfacing with their surround-

ings have been the holy grail of neuromorphic engineering. The effort of our community has concentrated on modeling neural structures and adaptive mechanisms in biology as much as it has on efficient implementation in real-time micropower hardware.

However, despite steady advances in the scaling of VLSI technology, which promises to deliver more transistors on a single chip than neurons in our brain, it is neither feasible nor advisable to integrate the full functionality of a complete nervous system on a single chip. Early experimentation with neuromorphic systems revealed the need for a multi-chip approach and a communication protocol between chips to implement large systems in a modular and scalable fashion. Thus, the address-event representation (AER) protocol was developed over a decade ago and quickly became a universal 'language' for neuro-morphic engineering systems to communicate neural spikes between chips.1-7 However, AER is now used for func-



tions in addition to inter-chip communication. The *Silicon Cortex* project proposed using AER to connect detailed compartmental models of neurons and synapses on multiple chips,<sup>8,9</sup> and a few different groups have used AER to implement synaptic connectivity.<sup>47</sup>

Here we will concentrate on our integrate-and-fire array transceiver (IFAT) chips, which can be used to implement large-scale neural networks in silicon with both synaptic connectivity and synaptic plasticity in the address-domain.<sup>10,11</sup> The newest IFAT chip<sup>12</sup> implements 2,400 silicon neurons, each with a single dynamically-programmable conductance-like synapse: both the synaptic 'conductance' and the synaptic driving potential can vary for each incoming event. Rather than hardwiring connections between cells, the network architecture and synaptic parameters are stored off-chip in a RAM-based look-up table (LUT). An external digital micro-controller (MCU) provides the appropriate signals to configure synapses and route spikes to their respective targets via an asynchronous AER bus. A block diagram of the system is shown in Figure 1.

During normal operation, the event-driven microcontroller is activated when a presynaptic neuron generates a spike. The cell's address is used as an index into the LUT and the data stored at that location in RAM specifies one or more postsynaptic targets with their associated synaptic weights and driving potentials. The MCU then provides signals to the IFAT to configure each synapse and sends the events serially. Any postsynaptic spikes generated by this process can either be sent back to

### In this issue:

- Telluride: Call for applications
- Smart building research at ETH/Caltech
- Wide dynamic range imaging from Ben Gurion
- University of Oslo on using the time domain
- Johns Hopkins research on using the time domain in analog circuits
- Caltech and MBARI collaborate to see jellies
- Imperial College vision chips for biomedical imaging
- CNRS robotic flight guidance
- Laboratory Notes: The iLab Neuromorphic Vision C++ Toolkit from USC
- Library Essentials: Analog VLSI & Neural Systems
- Mark Tilden and WowWee Toys introduce the Robosapien

the IFAT (in recurrent mode) or sent off-chip (in feed-forward mode), depending on the data stored in RAM. Additionally, updates to the network can be implemented by modifying the LUT according to a spike-based learning rule computed by the MCU.<sup>11</sup>

A printed circuit board (Figure 2) inte-



Figure 2. Printed circuit board integrating all components of the IEAT system.

grates the components of the IFAT system, including 9,600 neurons on four IFAT chips, 128MB of non-volatile SRAM, a high-speed 8bit voltage DAC, a 200MHz FPGA, and a 32bit digital I/O (DIO) interface. The DAC is used to control synaptic driving potentials, while synaptic weights are specified by three separate fields in the LUT: one each for the size of the postsynaptic potential, the number of events to send, and the probability of event transmission. External AER-compliant hardware or a peripheral computer interface

Vogelstein, continued p. 9

# **Beyond address-event communication...** from cover

can communicate with the IFAT through the DIO. The system is capable of implementing over four million synapses.

Previous generations of the IFAT system<sup>10</sup> have served a variety of applications. For instance, Laplacian filters were implemented to isolate vertical edges on static images:<sup>10</sup> a task that ran two orders of magnitude faster in hardware than in simulation. Similar network architectures can be employed to compute arbitrary filter kernels by varying the pattern of lateral connections between neurons. Even more interesting applications arise by extending address-event synaptic connectivity to address-domain synaptic plasticity. We implemented spike-based learning rules by monitoring the AER bus and dynamically updating the LUT.11 Using this strategy with a form of spike-timing dependent plasticity (STDP), we constructed a network that could

## On using the time domain...

#### from p. 5

a nuisance, is certainly not common among electronic engineers. This view, inspired by emerging neurophysiological coding models, can definitely give new impulse to circuit designs.

#### P. Häfliger

University of Oslo, Norway E-mail: hafliger@ifi.uio.no

#### References

 A. Bofill, A. F. Murray, and D.P. Thompson, Circuits for VLSI implementation of temporally asymmetric Hebbian learning, Advances in Neural Information Processing Systems (NIPS) 14, MIT Press, Cambridge, 2001.
S. Fusi, M. Annunziato, D. Badoni, A. Salamon, and D.J. Amit, "Spike-driven synaptic plasticity: theory, simulation, VLSI implementation, Neural Computation 12, pp. 2227-2258, 2000. detect correlated inputs and group them together. Subsequent work by other groups has demonstrated that the resulting networks are capable of preserving spike synchrony across multiple levels of neural processing.<sup>13</sup> Finally, we recently built rudimentary neural spatiotemporal filters and used them to process a spike train produced by an AER retina.<sup>14</sup> By constructing an array of similar elements and combining the appropriate outputs, it is possible to construct velocity-selective cells similar to those found in the medial-temporal cortical area (MT) of the human brain.<sup>15</sup>

We believe that by combining analog VLSI hardware with a digital microcontroller and RAM, reconfigurable hardware neural networks provide the 'best of both worlds': analog cells efficiently model sophisticated neural dynamics in real-time, while network architectures can be reconfigured and adapted

3. W. Gerstner, R. Kempter, J. L. van Hemmen, and H. Wagner. A neuronal learning rule for sub-millisecond temporal coding. Nature 383, pp. 76-78, 1996.

4. P. Häfliger, M. Mahowald, and L. Watts. *A spike based learning neuron in analog VLSI*, Advances in neural information processing systems 9, pp. 692-698, 1996. 5. P. Häfliger. A spike based learning rule and its implementation in analog hardware. Ph.D. thesis, ETH Zurich, Switzerland, 2000.

http://www.ifi.uio.no/~hafliger.

6. P. Häfliger and H. Kolle Riis. A multi-level static memory cell, Proc. IEEE ISCAS 1, pp. 22-25, Bangkok, Thailand, May 2003.

7. J. Kramer, R. Sarpeshkar, and C. Koch, *Pulse-based analog VLSI velocity sensors*, IEEE Trans. on Circ. and Sys.-II 44 (2), pp. 86-100, February 1997.

 J. Lazzaro and C. Mead, A silicon model of auditory localization, Neural Computation 1, pp. 41-70, 1989.
P. Häfliger and E. Jørgensen Aasebo, A rank encoder: Adaptive analog to digital conversion exploiting time domain spike signal processing. Analog Integrated Circuits and

Signal Processing, accepted for publication in 2004. 10. P. Häfliger and E. Bergh, *An integrated circuit computing shift in stereopictures using time domain spike signals*, Proc. 2002 NORCHIP 20, Københaven, November 2002.

#### **Biologically Inspired Cognitive Systems (BICS 2004)** Stirling, Scotland, August 29 - September 1 2004

Includes tracks on:

#### **Neuromorphic Systems**

Sensor and Sensory Systems - Computer Vision, Audition, Olfaction; High-level Perception; Intelligent Sensor Fusion and Sensor/motor integration; Smart Human-machine Communication; Autonomous Robots; Behavior-based Control; and Hardware and Software Implementations.

#### Neurophysiologically Inspired Models

Neuro-physiological foundations; Spiking neuron models and neuron assemblies; Models of brain centers and sensory pathways; Sensation, Perception and Attention; Spatio-temporal Orientation; Reactive Behaviour

Paper call deadline extended to 29 February 2004.

http://www.icsc-naiso.org/conferences/bics2004/bics-cfp.html

in-site. The newest of these systems provide a number of advantages over previous designs, including more neurons, a richer parameter space, more biologically plausible dynamics, and a higher degree of inter-connectivity and plasticity. We expect them to serve as useful tools for future investigations of learning in large-scale neural networks. We invite the readers to contact us for collaborative opportunities on modeling of large-scale biological neural circuits.

## R. Jacob Vogelstein\*, Udayan Mallik, and Gert Cauwenberghs

Johns Hopkins University {jvogelst,udayan,gert}@jhu.edu \*Corresponding author

#### References

1. M. Sivilotti, Wiring considerations in Analog VLSI Systems, with application to Field-Programmable Networks, PhD thesis, Cal. Inst. of Tech., 1991.

2. M. Mahowald, An analog VLSI system for stereoscopic vision, Kluwer Academic Publishers, Boston, MA, 1994.

3. J. Lazzaro, J. Wawrzynek, M. Mahowald, M. Sivilotti, and D. Gillespie, *Silicon auditory processors as computer peripherals*, **IEEE Trans. Neural Networks 4** (3), pp. 523-528, 1993.

4. K. A. Boahen, Point-to-point connectivity between neuromorphic chips using address events, IEEE Trans. Circuits and Systems II 47 (5), pp. 416-434, 2000.

5. C. M. Higgins and C. Koch, *Multi-chip neuromorphic motion processing*, in **Proc. 20th Anniversary Conference on Advanced Research in VLSI** (D. Wills and S. DeWeerth, eds.), pp. 309-323, IEEE Computer Society, Los Alamitos, CA, 1999.

6. S. Liu, J. Kramer, G. Indiveri, T. Delbruck, and R. Douglas, *Orientation-selective aVLSI spiking neurons*, in Advances in Neural Information Processing Systems 14, MIT Press, Cambridge, MA, 2002.

7. Interchip communication project group, **Report on** the 2001 Workshop on Neuromorphic Engineering, Telluride, CO, 2001.

 S. R. Deiss, R. J. Douglas, and A. M. Whatley, A Pulse-Coded Communications Infrastructure for Neuromorphic Systems, in Pulsed Neural Networks (W. Maass and C. M. Bishop, eds.), pp. 157–178, MIT Press, Cambridge, MA, 1999.

9. M. Mahowald and R. Douglas, A silicon neuron, Nature 354, pp. 515-518, 1991.

10. D. H. Goldberg, G. Cauwenberghs, and A. G. Andreou, *Probabilistic synaptic weighting in a reconfigurable network of VLSI integrate-and-fire neurons*, Neural Networks 14 (6-7), pp. 781-793, 2001.

11. R. J. Vogelstein, F. Tenore, R. Philipp, M. S. Adlerstein, D. H. Goldberg, and G. Cauwenberghs, *Spike timing-dependent plasticity in the address domain*, in Advances in Neural Information Processing Systems 15, MIT Press, Cambridge, MA, 2003.

12. R. J. Vogelstein, U. Mallik, and G. Cauwenberghs, Silicon spike-based synaptic array and address-event transceiver; in Proc. 2004 IEEE International Symposium on Circuits and Systems, Vancouver, Canada, 2004 (forthcoming).

13. A. Bofill-i-Petit, A. Murray, Synchrony detection by analogue VLSI neurons with bimodal STDP synapses, in Advances in Neural Information Processing Systems 16, MIT Press, Cambridge, MA, 2004.

14. R. J. Vogelstein, R. Philipp, P. Merolla, S. Kalik, and R. Etienne-Cummings, *Constructing spatiotemporal filters* with a reconfigurable neural array, **2003 Workshop on** Neuromorphic Engineering, Telluride, CO, 2003.

15. R. Etienne-Cummings, J. Van der Spiegel, and P. Mueller, Hardware Implementation of a Visual Motion Pixel using Oriented Spatiotemporal Neural Filters, IEEE Trans. Circuits and System II 46 (9), pp. 1121-1136, 1999.